

Assessment Report (Monkfish)

May 18, 2010

Appendix A.1a: Initial Analyses of Depletion Experiments

Initial Analyses of Depletion Experiments for Monkfish

April 12, 2010

Southern Demersal Working Group

SARC 50

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The Catchability Coefficient

A Fundamental Property in Fisheries Science

- Catchability is a scalar that translates indices of relative abundance to absolute abundance.
- The catchability coefficient q was first defined in 1918 by Baranov who called it the “elemental intensity of fishing” which is the fractional reduction in average density per application of a unit of effort.
- Catchability is a parameter in every fisheries model that combines indices of abundance and estimates of total removals. If the model estimates absolute biomass or numbers, then there is a q buried in the equation sets.
- $\text{Index} = \text{Catchability} \times \text{Absolute Abundance}$
- Model-based estimates of catchability can be a source of instability in dynamic models.



Simple Depletion Models

Leslie and Davis 1939, DeLury 1947

Primary assumptions include

- 1) All extant individuals have the same probability of being caught in a sample,
- 2) Expected catch in a sample is proportional to sampling effort,
- 3) Units of sampling effort are independent and additive,
- 4) Catch depends on the cumulative catch of preceding samples, and
- 5) All removals are known.

Assumptions are violated in subtle but important ways

- Variations with size of animal
- Changes in availability to gear
- Changes in behavior of animals
- Loss of animals as a result of sampling



The Basic Depletion Model

Catch = P(Capture|Encounter) x P(Encounter) x Population

$$(1) \quad E(C) = e \left(\frac{a}{A} \right) N$$

Where

e = gear efficiency

a = area swept by unit of gear

A = Total area occupied by population

N = total population size

q = e (a/A)

Note that density $D = N/A$ so that

$$C = e a D$$



Deriving the Recursive Model

- Consider a population of size N_0 in an area of size A such that the initial density is $D_0 = N_0/A$.

Let $C_j = q N_{j-1}$ and $N_{j+1} = N_j - C_j$

- Then $C_1 = q N_0$ and $N_1 = N_0 - C_1$
- Then $C_2 = q N_1$ and $N_2 = N_1 - C_2$
- Then $C_3 = q N_2$ and $N_3 = N_2 - C_3$
- Lather, rinse, repeat to get

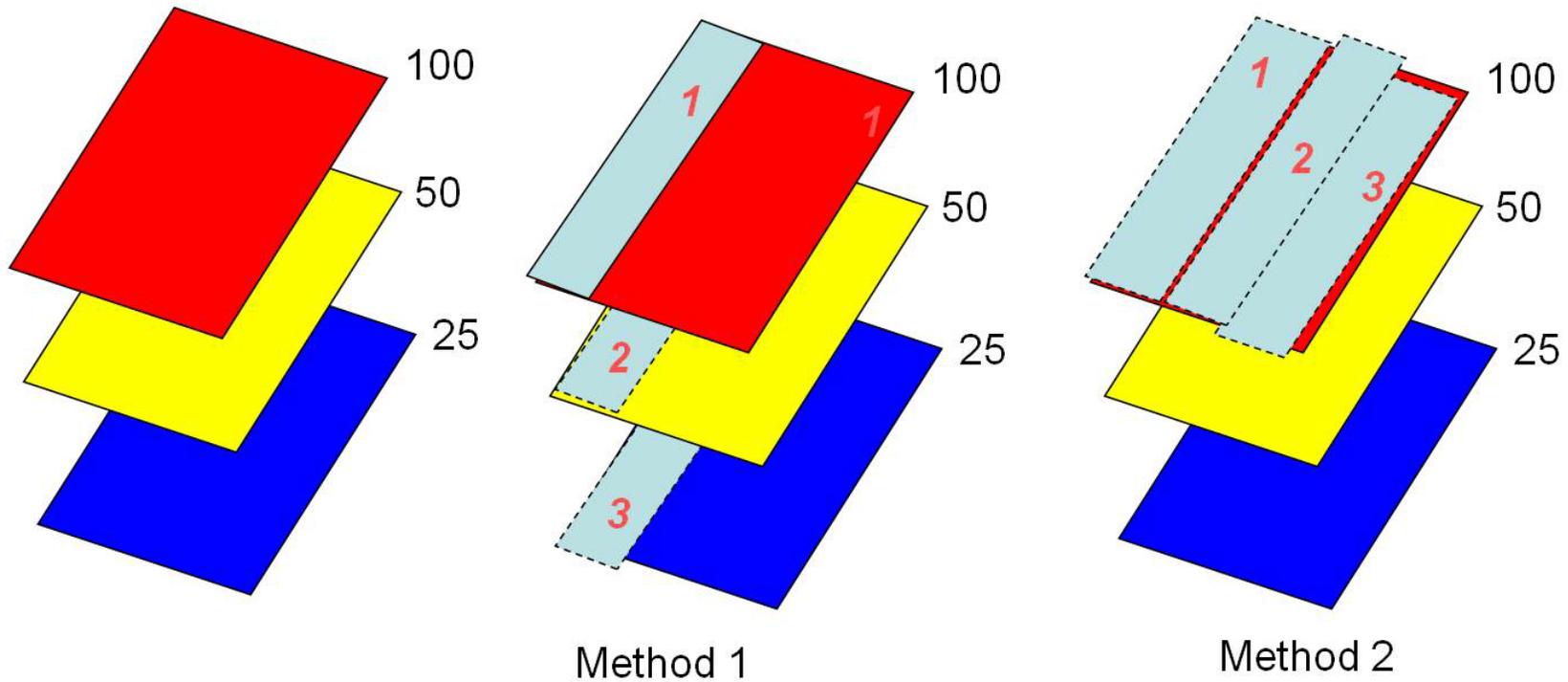
$$(2) \quad E(C_i) = q(N_0 - T_{i-1})$$

$$\text{where } T_{i-1} = \sum_{j=1}^{i-1} C_j \text{ ,}$$

for $i = \text{tow number}$.

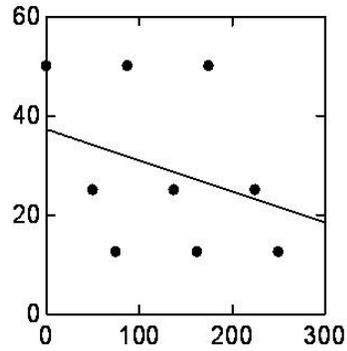
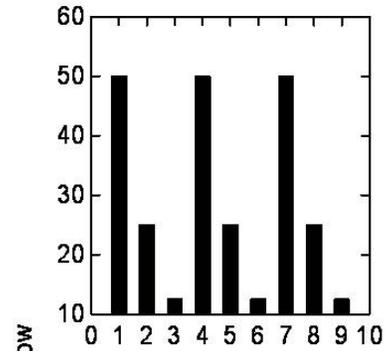
Why Space Matters

- Consider a population that exists over some area A and that the population N is sessile. Assume that the sampling device has a 50% efficiency and that it can sample 1/3 of the area per unit effort.



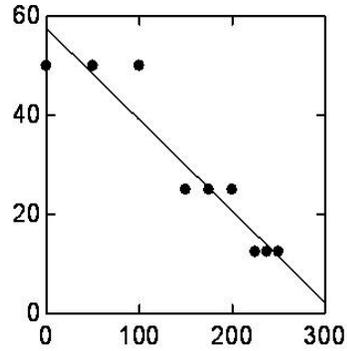
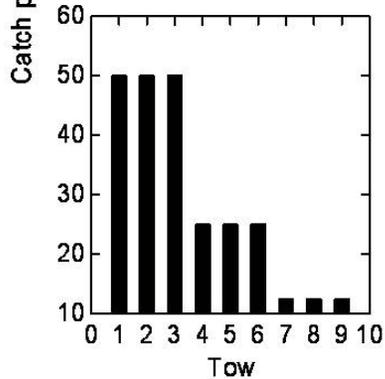
Toy Example: Why spatial pattern of depletion tows matters.

True Population = 300
True Efficiency=0.5

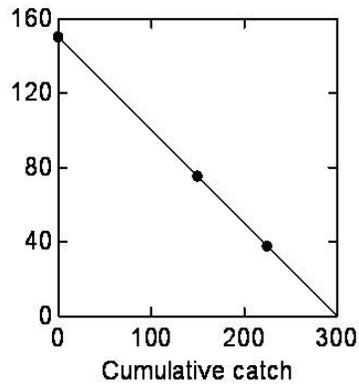
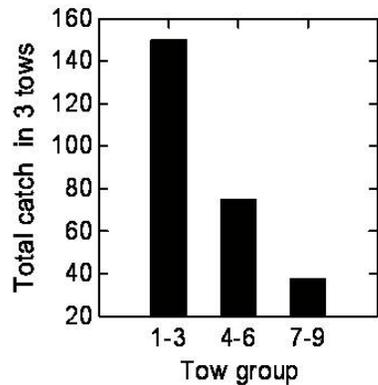


MLE(1) N=595, Efficiency=0.06

If the catch patterns are incorrectly assumed to be the result of random variability, then MLE estimates are biased.



MLE(2) N=312 Efficiency=0.18

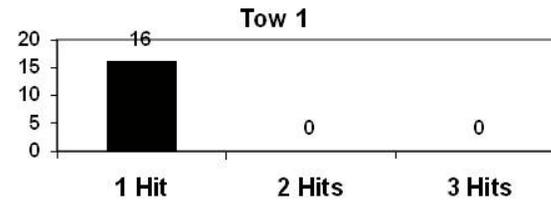
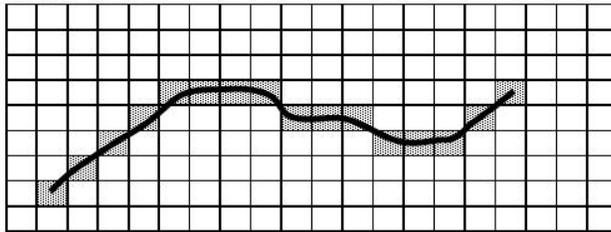


Pooling of samples can work *IF* you know how to aggregate the tows.

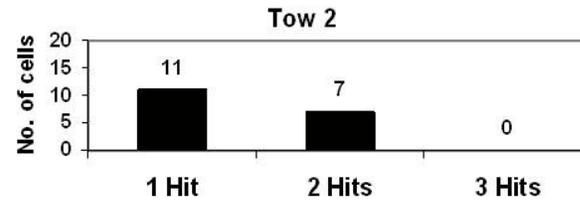
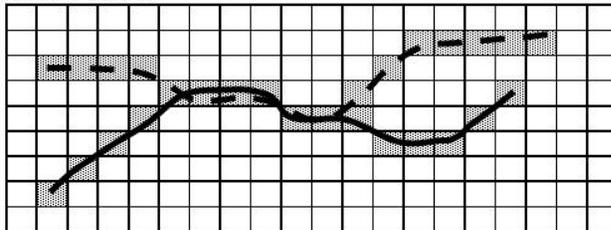
MLE(3) N=300 Efficiency=0.50

Consider a spatial pattern where the precision of sampling cannot be controlled but it is possible to “know” where the gear is, after the sample is taken. Clearly, the expected catch is a function of the amount of overlap between successive tows.

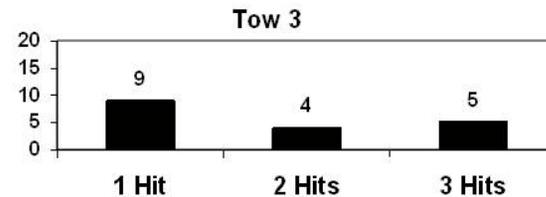
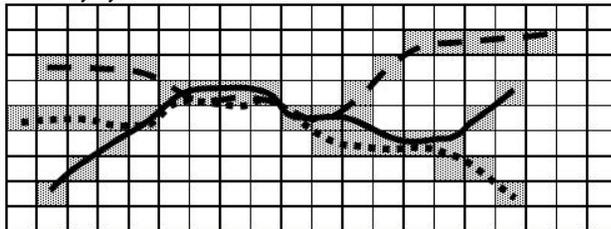
Tow 1



Tow 1 and 2



Tow 1, 2, and 3





To solve the problem, it is necessary to recast the depletion problem in terms of density per unit area, AND to consider a sample as a string of quadrats or patches.

N_0	$D_0 = N_0/A$
$N_1 = N_0 - C_1$ $= N_0 - e(a/A)N_0$ $= N_0(1 - e(a/A))$	$D_1 = N_1/A$ $= (N_0/A)(1 - e(a/A))$
$N_2 = N_1 - C_2$ $= N_0(1 - e(a/A)) - e(a/A)N_0(1 - e(a/A))$ $= N_0(1 - e(a/A))(1 - e(a/A))$ $= N_0(1 - e(a/A))^2$	$D_2 = N_2/A$ $= (N_0/A)(1 - e(a/A))^2$ $= D_0(1 - e(a/A))^2$
$N_3 = N_2 - C_3$ $= N_0(1 - e(a/A))^2 - e(a/A)N_0(1 - e(a/A))^2$ $= N_0(1 - e(a/A))^2(1 - e(a/A))$ $= N_0(1 - e(a/A))^3$	$D_3 = N_3/A$ $= (N_0/A)(1 - e(a/A))^3$ $= D_0(1 - e(a/A))^3$

The expected catch as a function of patch density.

- Via the miracle of recursive pluggation

$$(3) \quad E(C_j) = e a D_o \left(1 - e \left(\frac{a}{A} \right) \right)^{j-1}$$

- Now we need to extend this concept to a tow where a tow consists of a set of contiguous patches linked together. Record the number of times that a tow “hits” a particular patch. The first tow will consist of a set of quadrats with one hit each. The second tow, if it exactly overlaps the first, will consist of a set of quadrats with two hits each. Otherwise it will have a mix of 1 and 2 hit cells. The third tow can have some mix of 1, 2 or 3 hits. Etc. With some algebra you get

$$(4) \quad E(C_i) = e a_i D_o \sum_{j=1}^i f_{i,j} (1 - e \gamma)^{j-1}$$

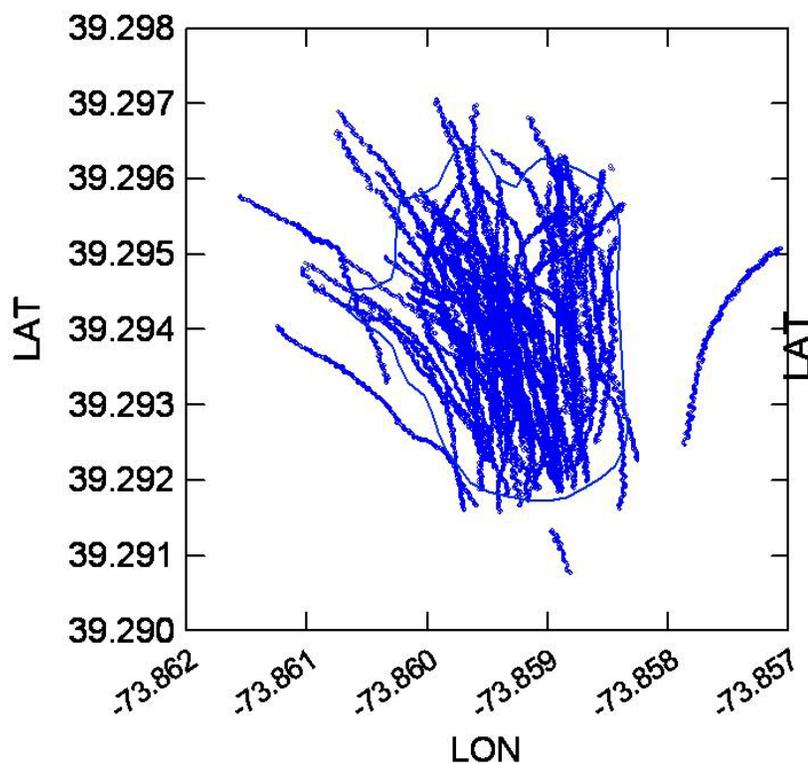
OK, where did the gamma come from and what is $f_{i,j}$?

$$(4) \quad E(C_i) = e a_i D_o \sum_{j=1}^i f_{i,j} (1 - e\gamma)^{j-1}$$

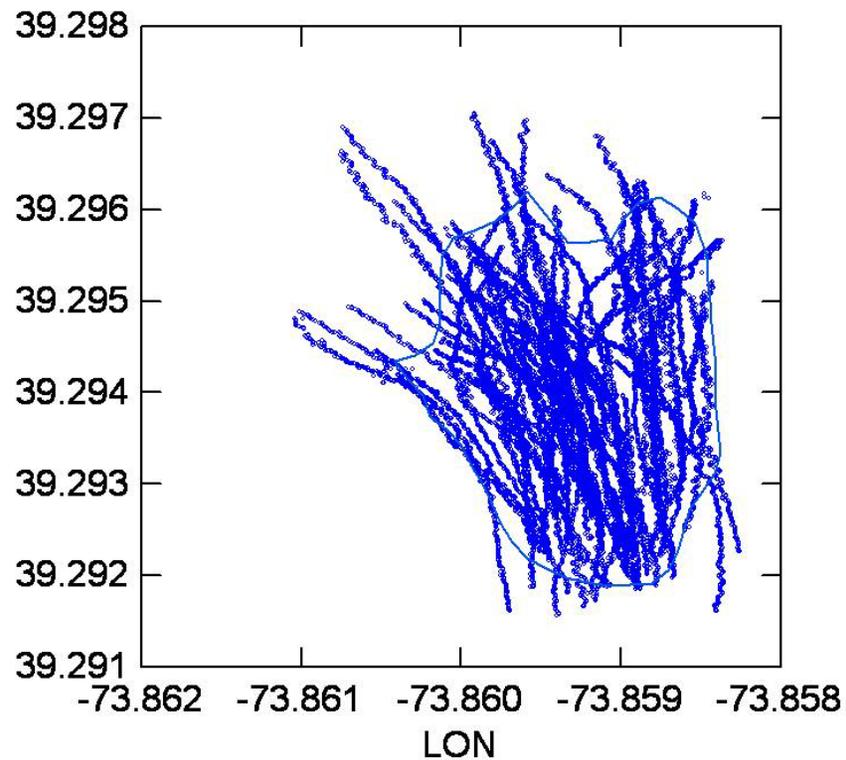
- $f_{i,j}$ is the fraction of a tow of swept area a_i that is hit j times
- Gamma is ratio of the sampling device width over the width of the patch. If the width of sampler is $\frac{1}{2}$ the width of the cell, then gamma = 0.5. Thus the patch size can increase in response to increasing uncertainty in the actual position of the sampling gear.
- Gamma can also be used to account for indirect effects of sampling which may occur in a variety of ways. More on this later.

Deriving the expected catch for a set of randomly overlapping tows. A depletion experiment on DE II

DE II Depl Exp ALL tows



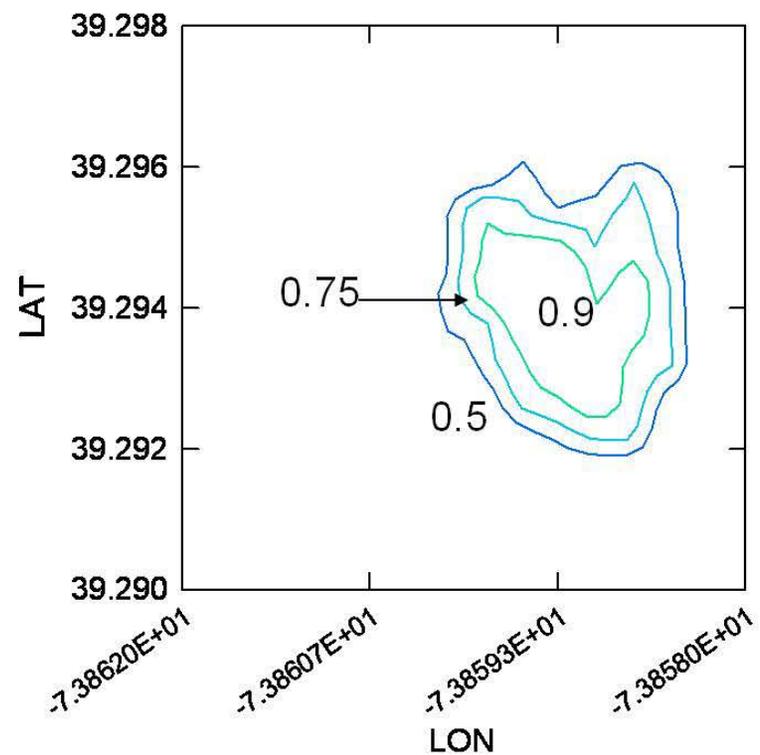
DE II Depl Exp w/o 118,120,122,153



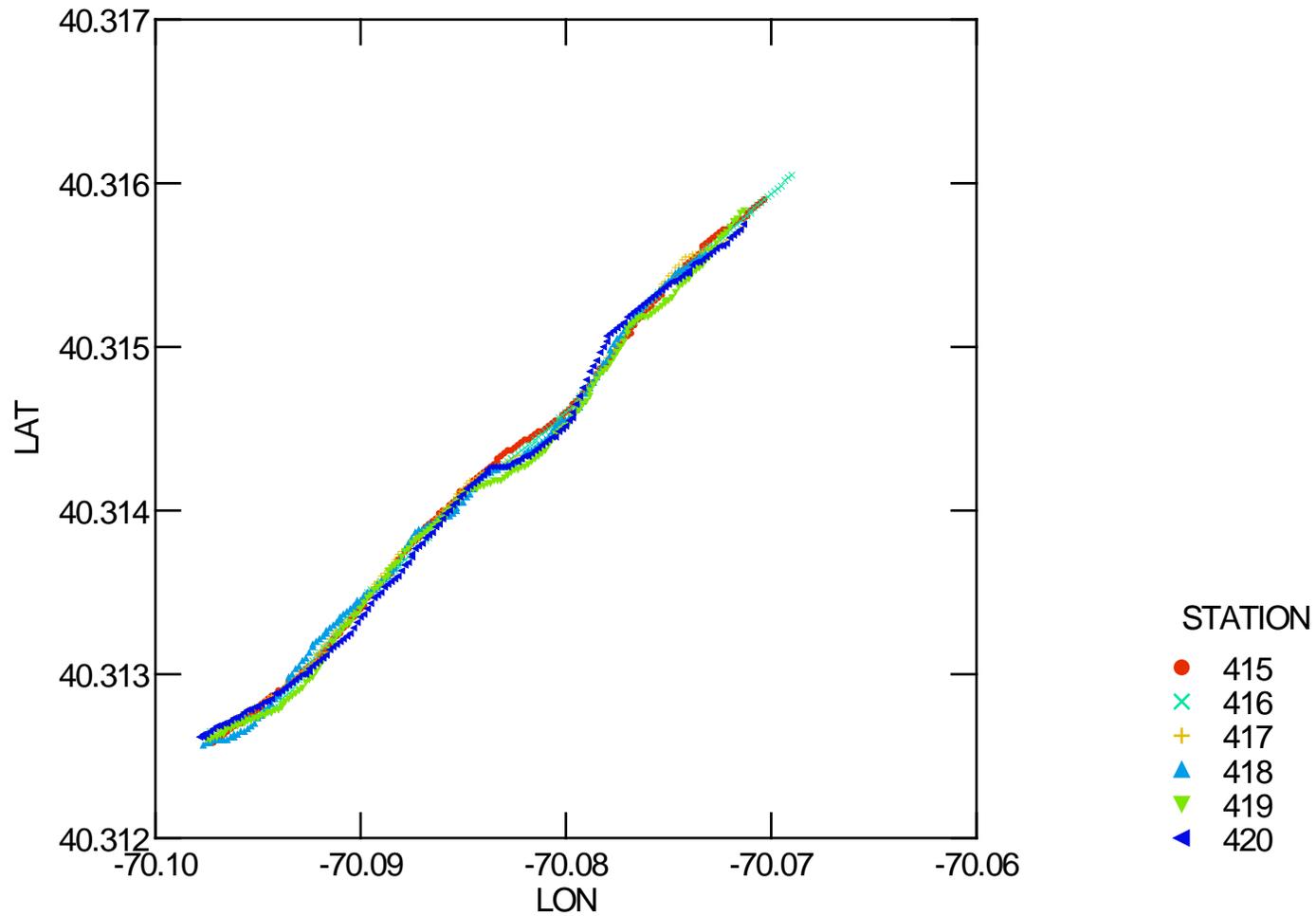


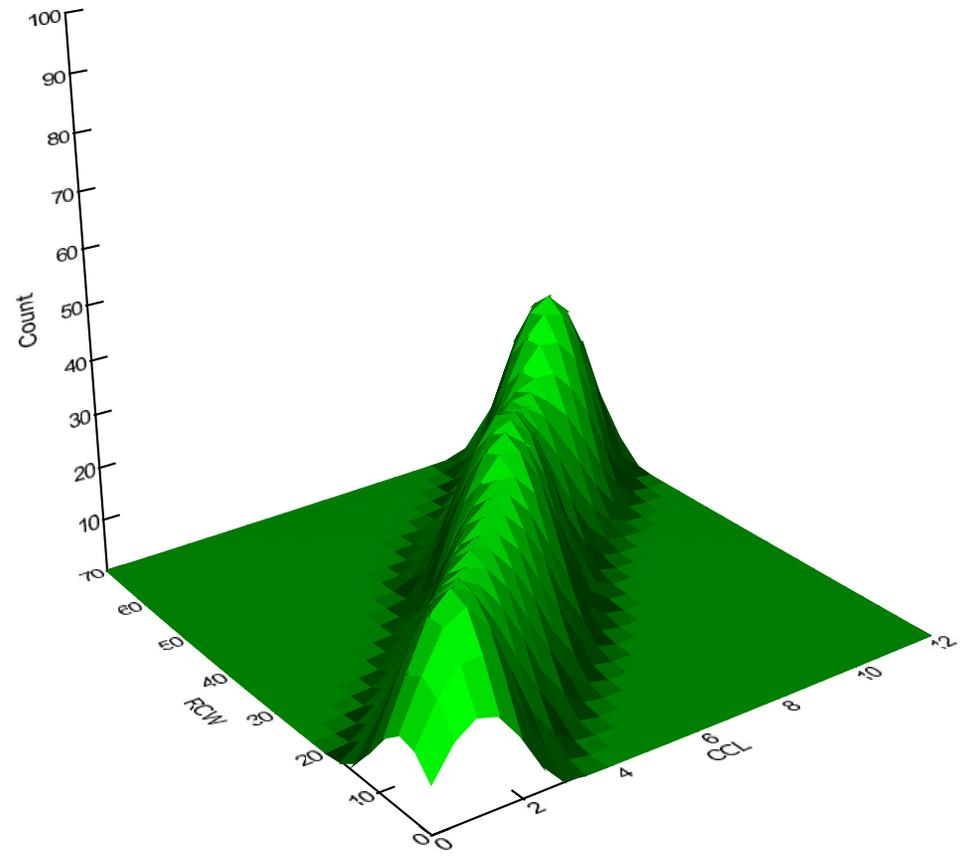
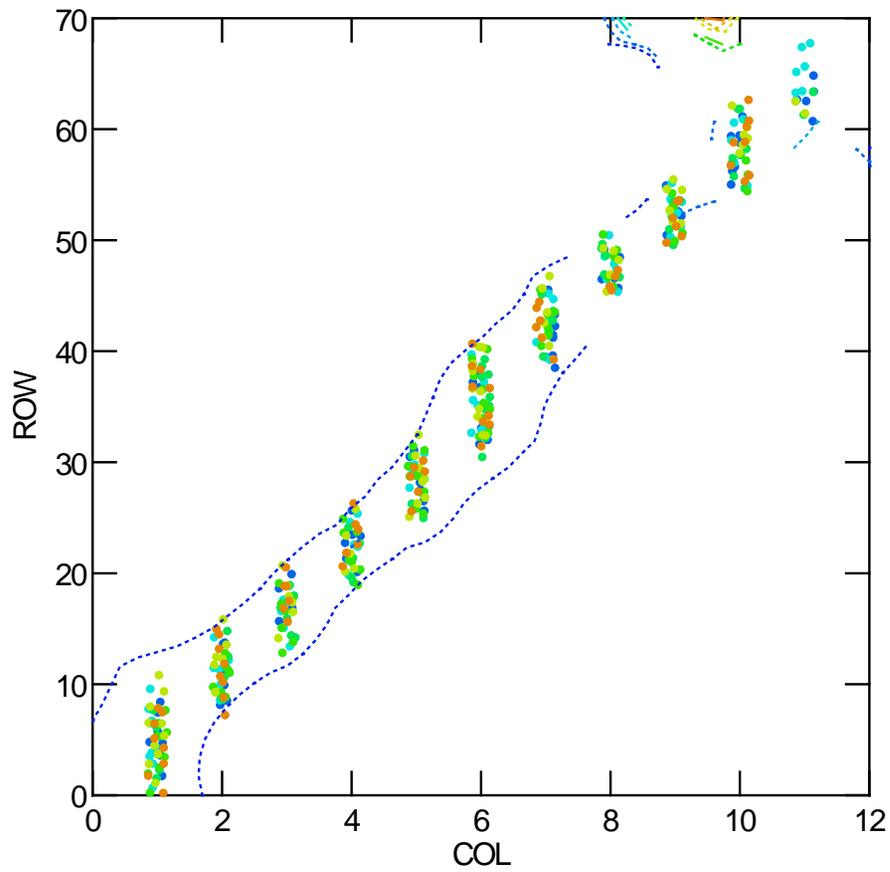
A kernel density can be used to illustrate to concentration of sampling intensity.

- DE II Depl Exp w/o 118,120,122,153

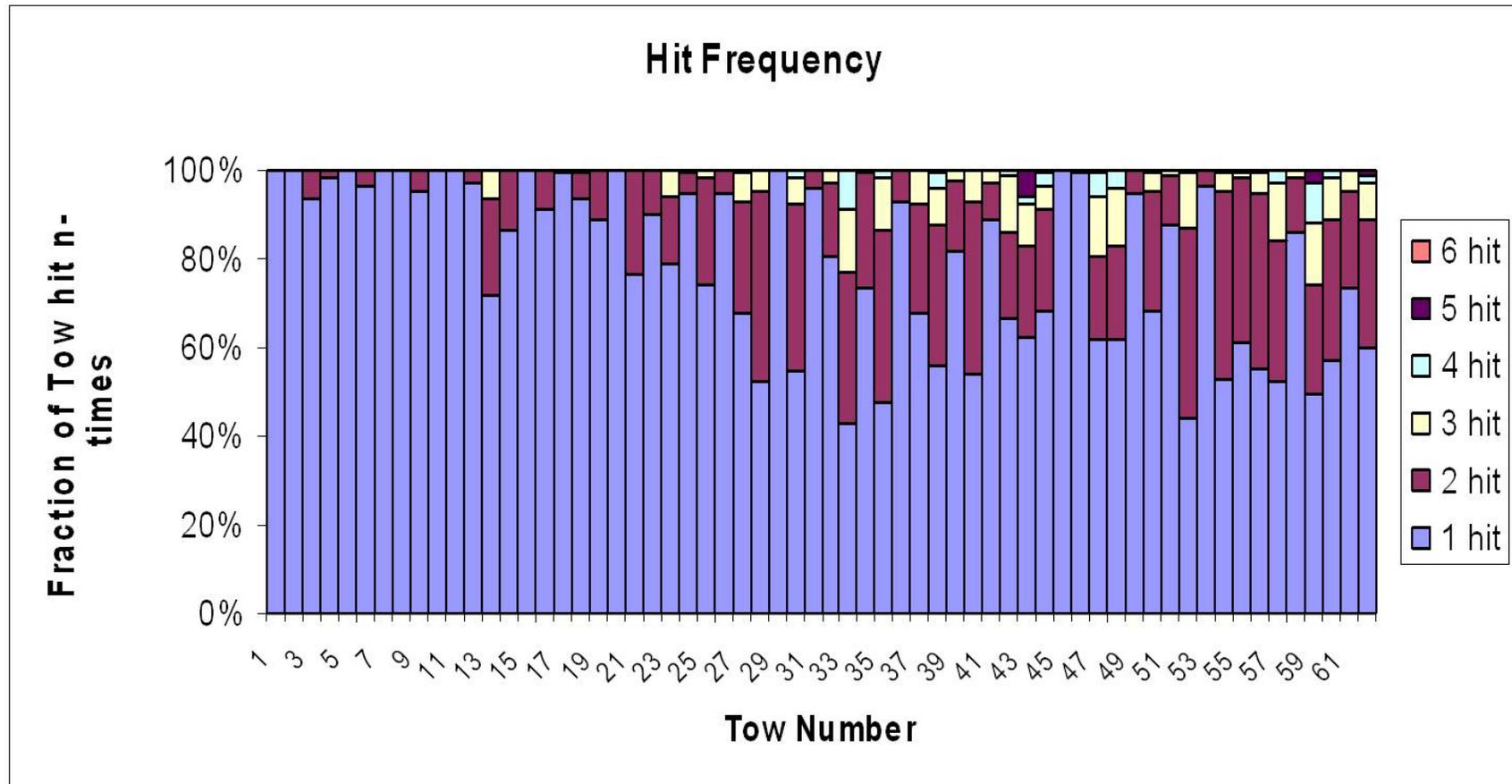


experiment #5

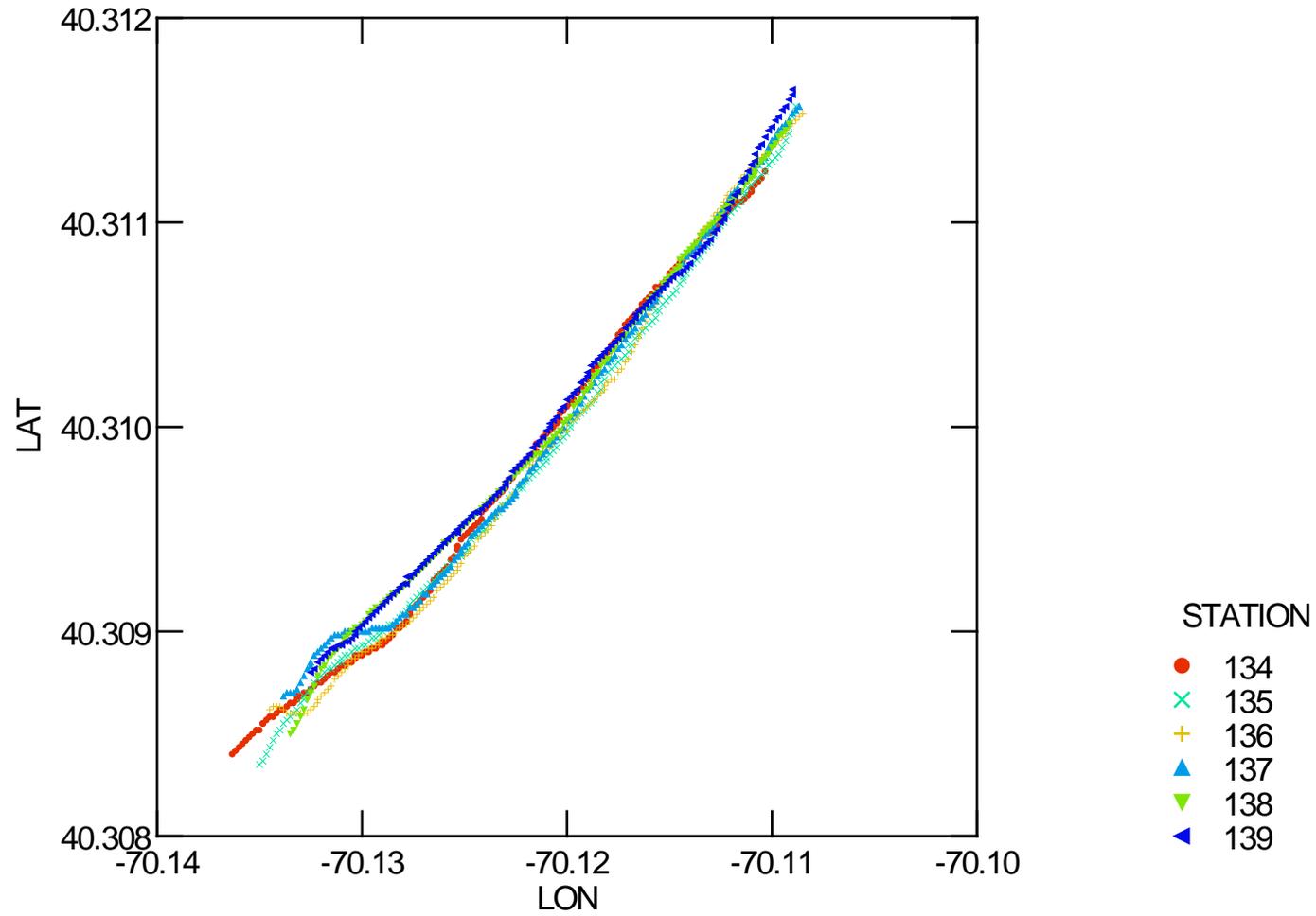


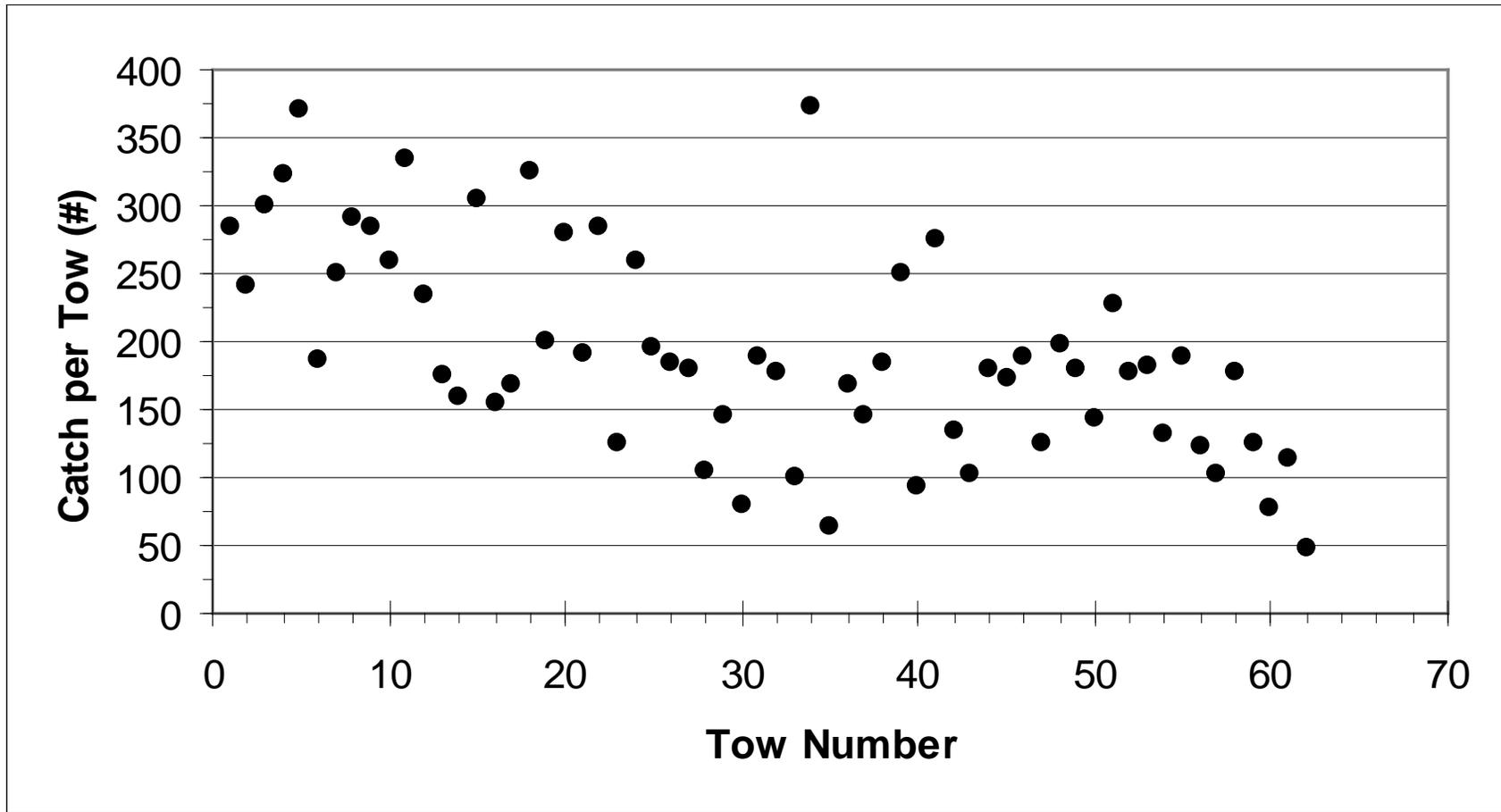


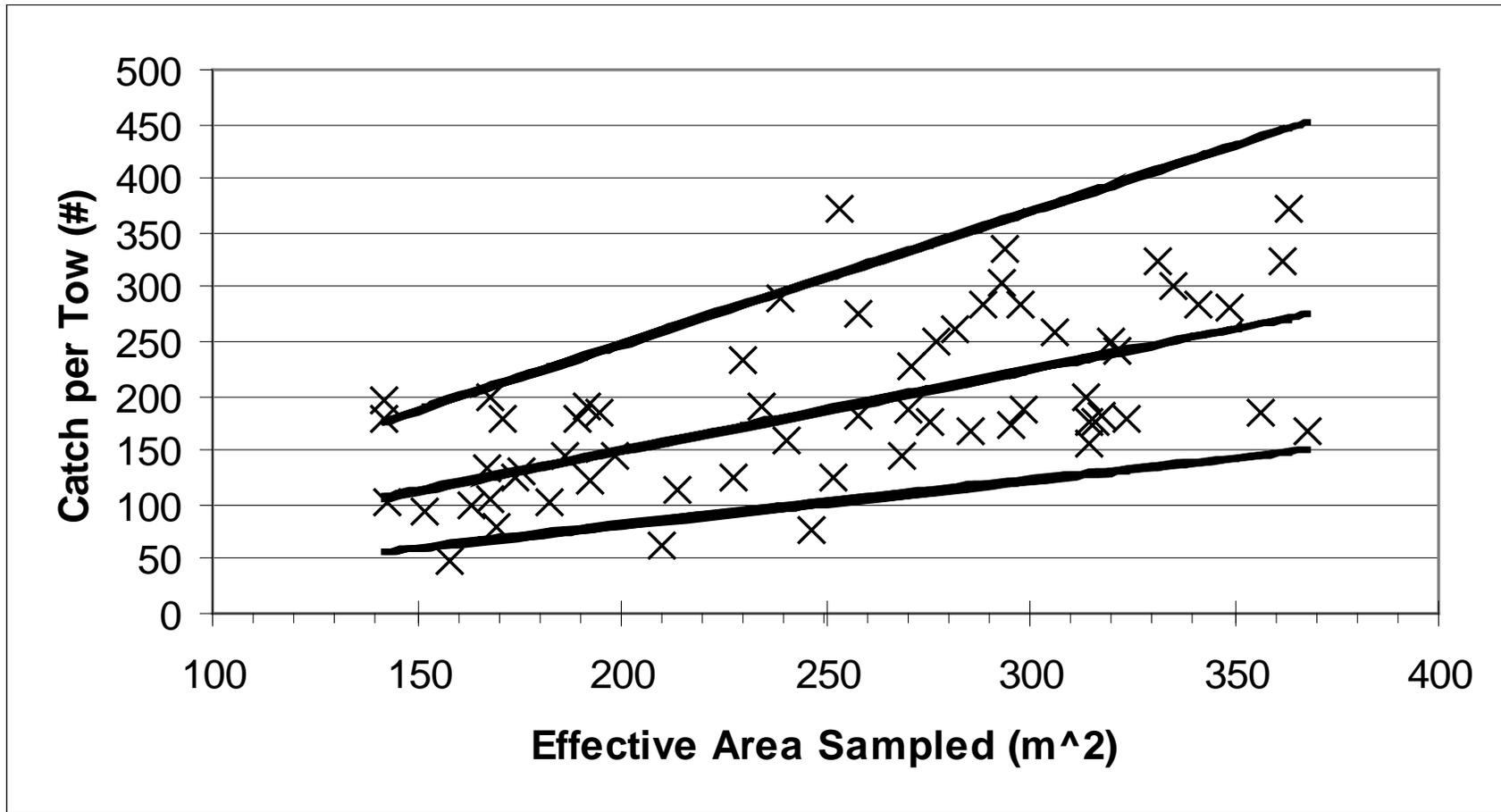
The hit frequency matrix for the Delaware II depletion experiment



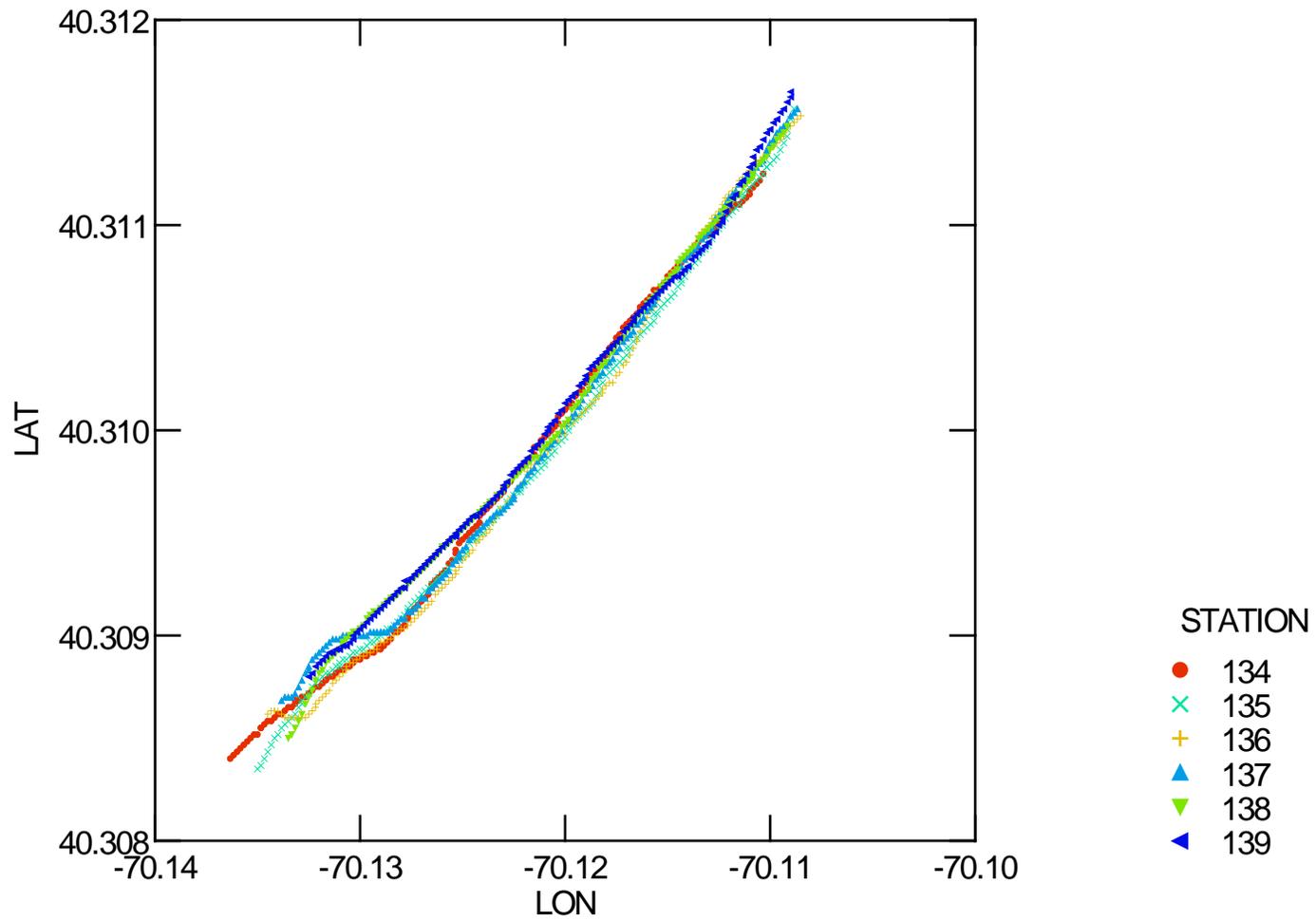
experiment #1



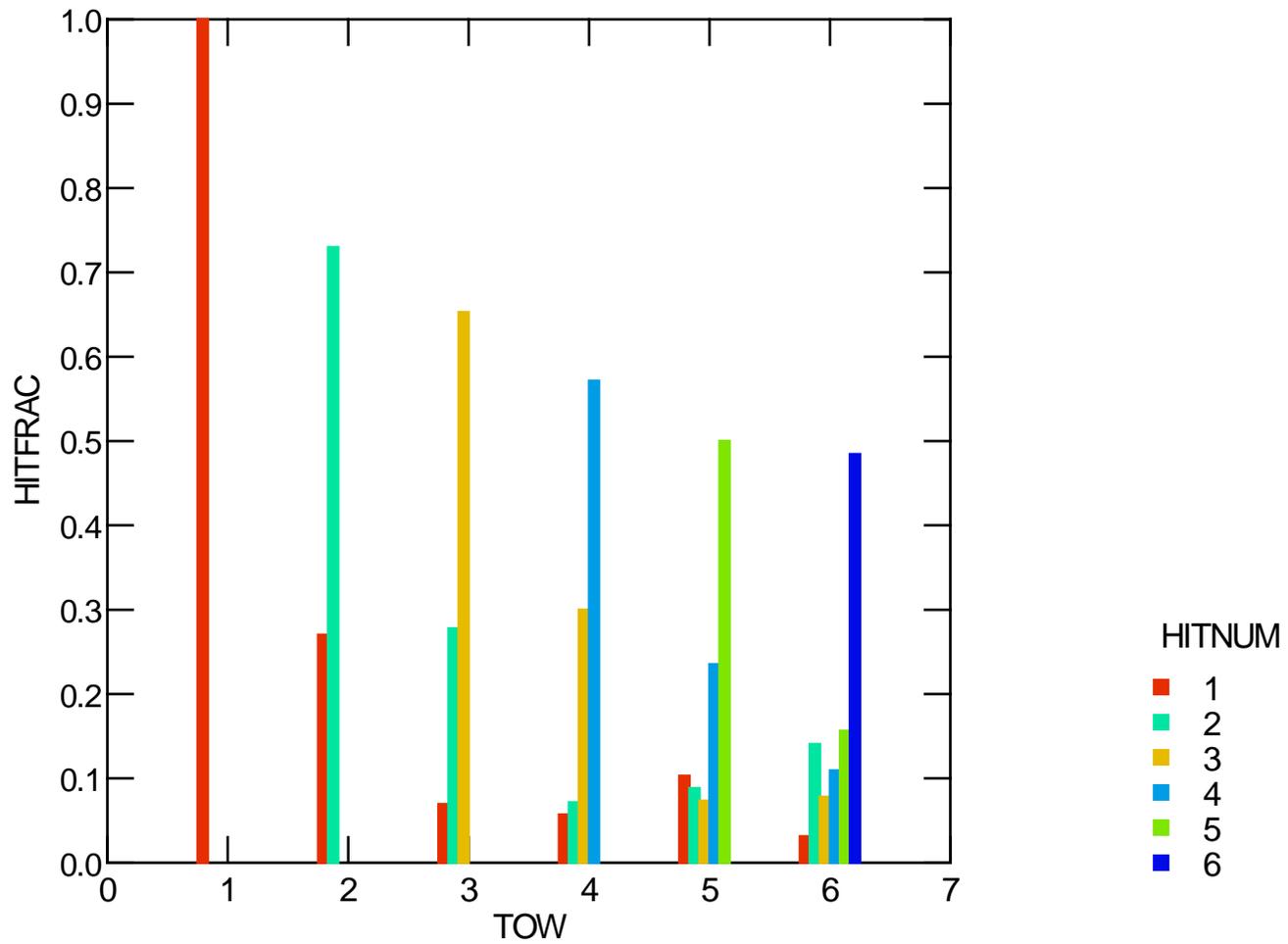




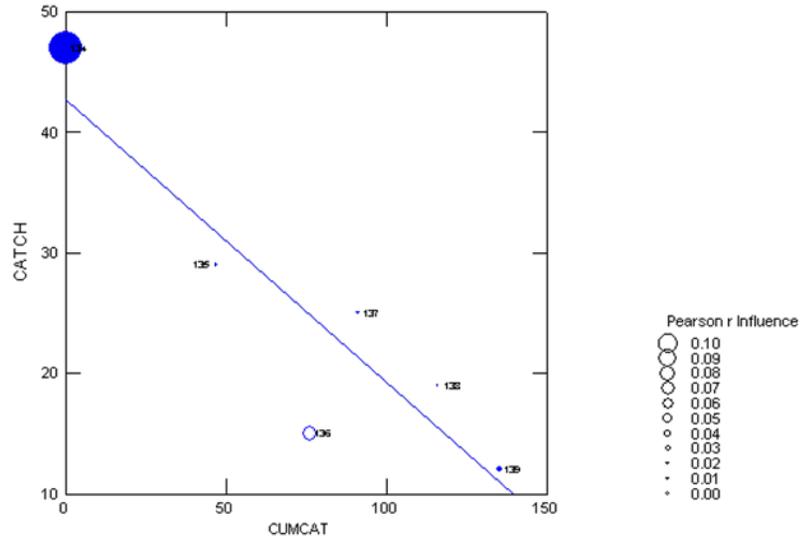
experiment #1



Experiment #1

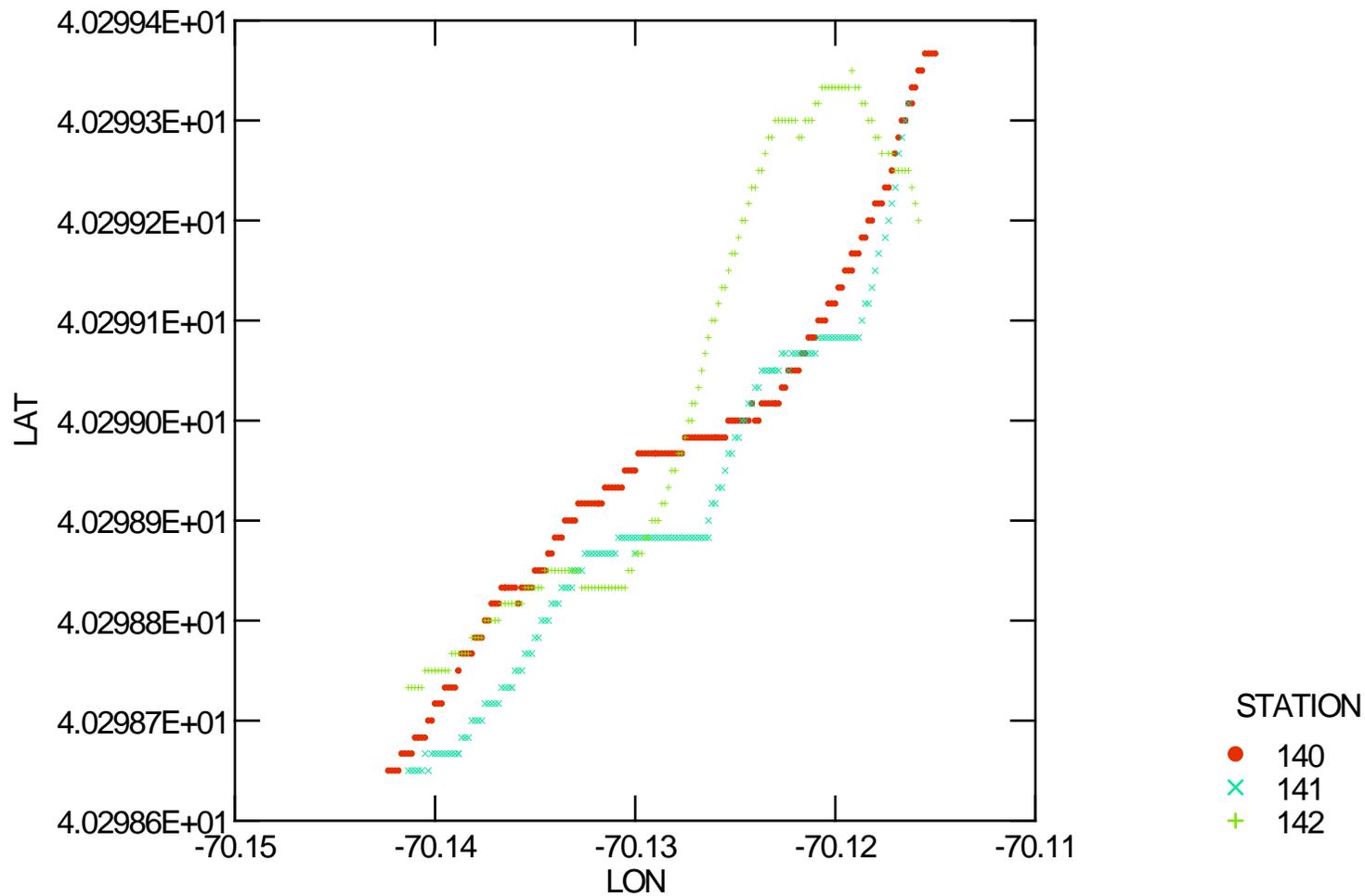


Experiment #1

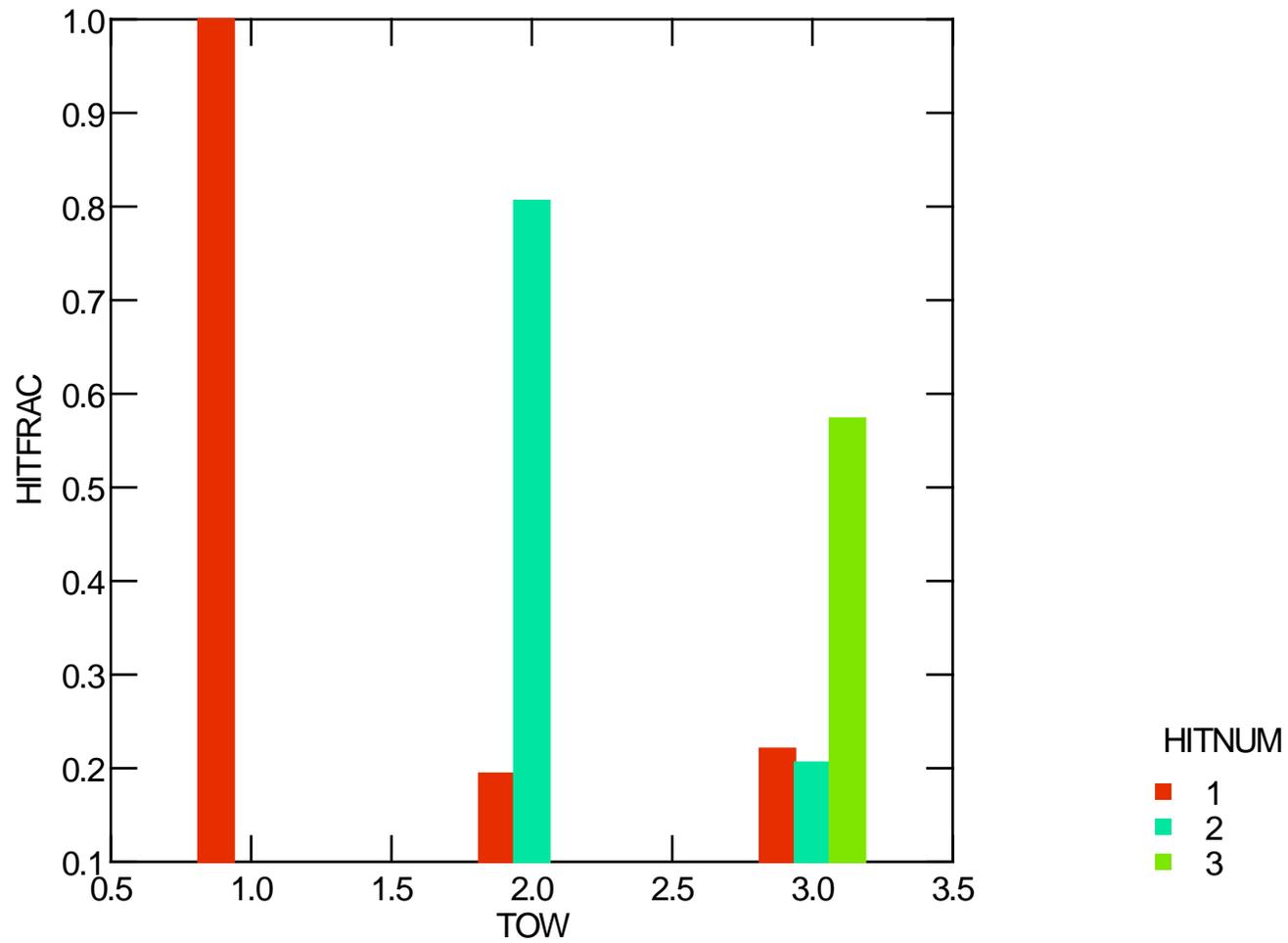


Tow	Area Swept	Efftv Area	C_5%	C_50%	C_pred	OBS	C_95%
CI 1	566598.0	194434.7	29.	41.	41.	47.	56.
CI 2	572557.0	157118.4	23.	34.	33.	29.	46.
CI 3	569490.0	120094.9	17.	26.	25.	15.	36.
CI 4	545629.0	90817.8	12.	20.	19.	25.	29.
CI 5	525474.0	78258.5	10.	17.	16.	19.	25.
CI 6	509265.0	62348.7	8.	14.	13.	12.	21.

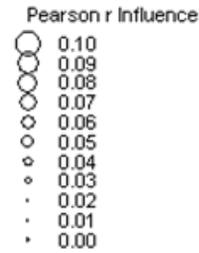
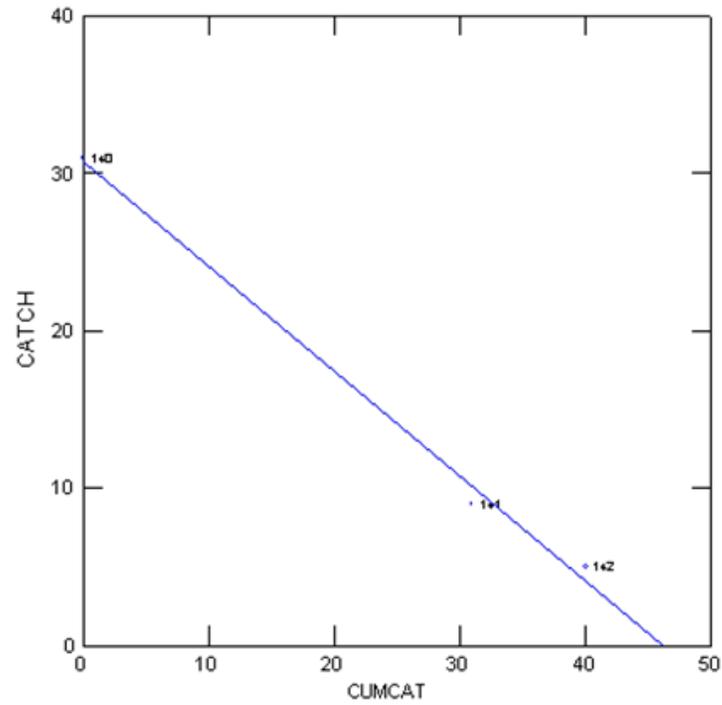
experiment #2



Experiment #2

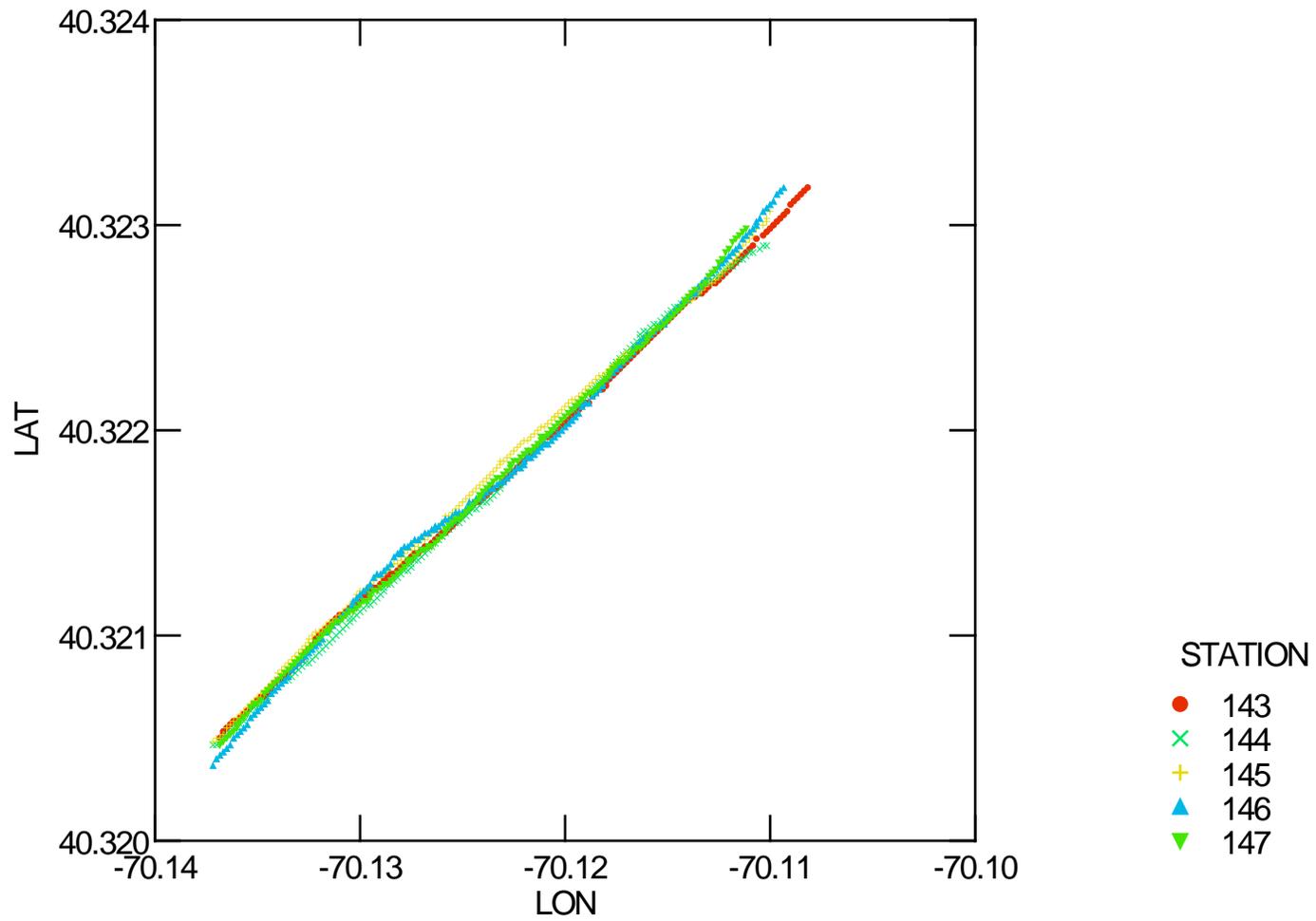


Experiment #2

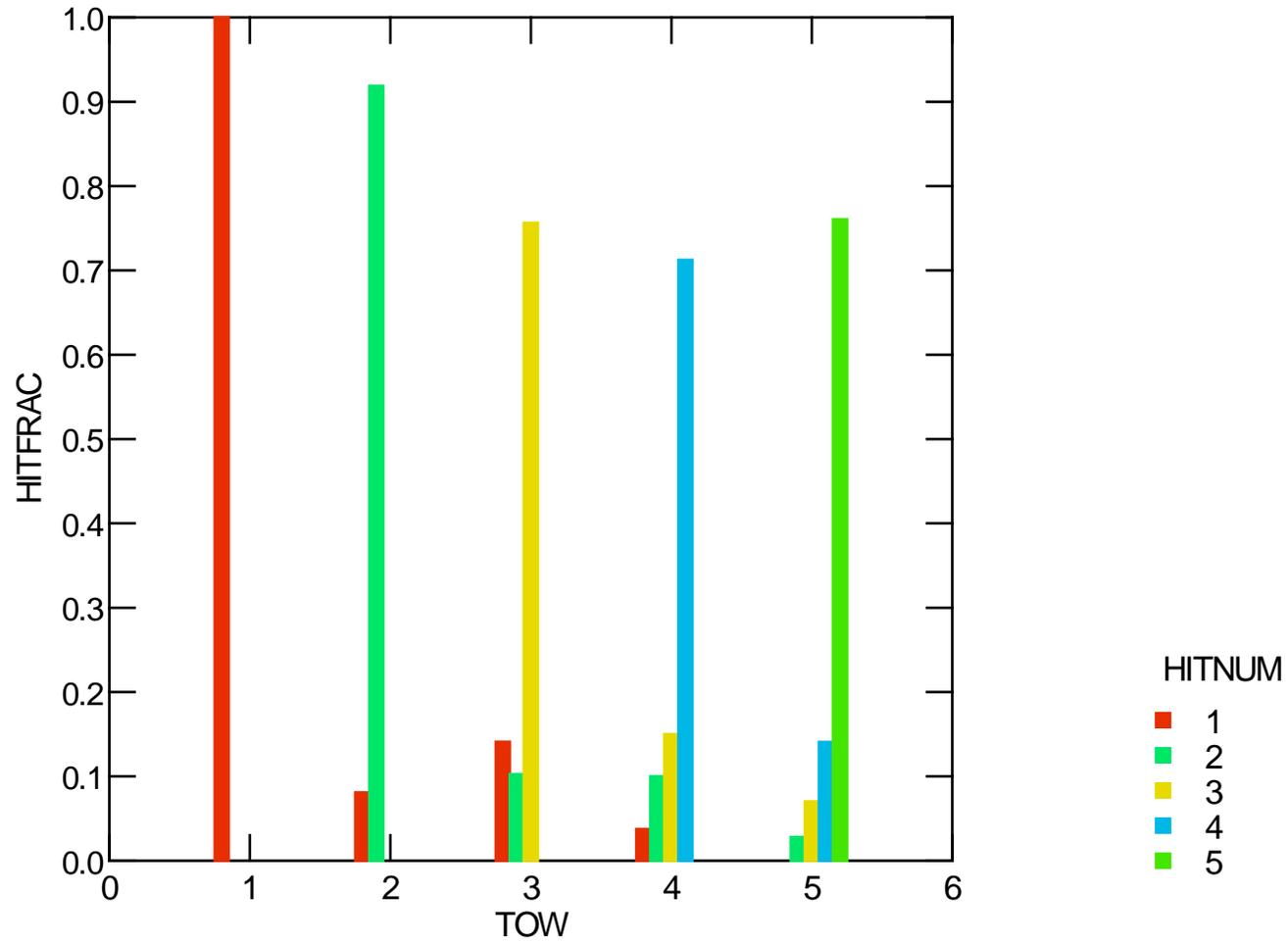


Tow	Area Swept	Efftv Area	C_5%	C_50%	C_pred	OBS	C_95%
CI 1	590158.0	560650.0	20.	28.	28.	31.	38.
CI 2	533897.0	196483.1	6.	10.	10.	9.	16.
CI 3	545551.0	157031.4	4.	9.	8.	5.	14.

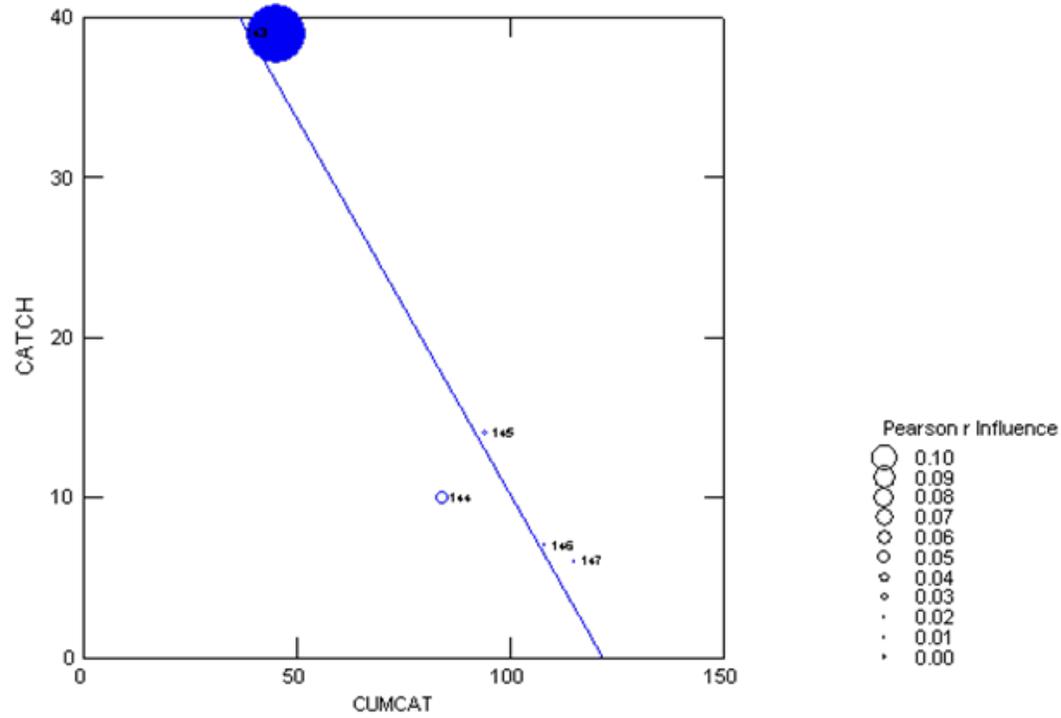
experiment #3



Experiment #3

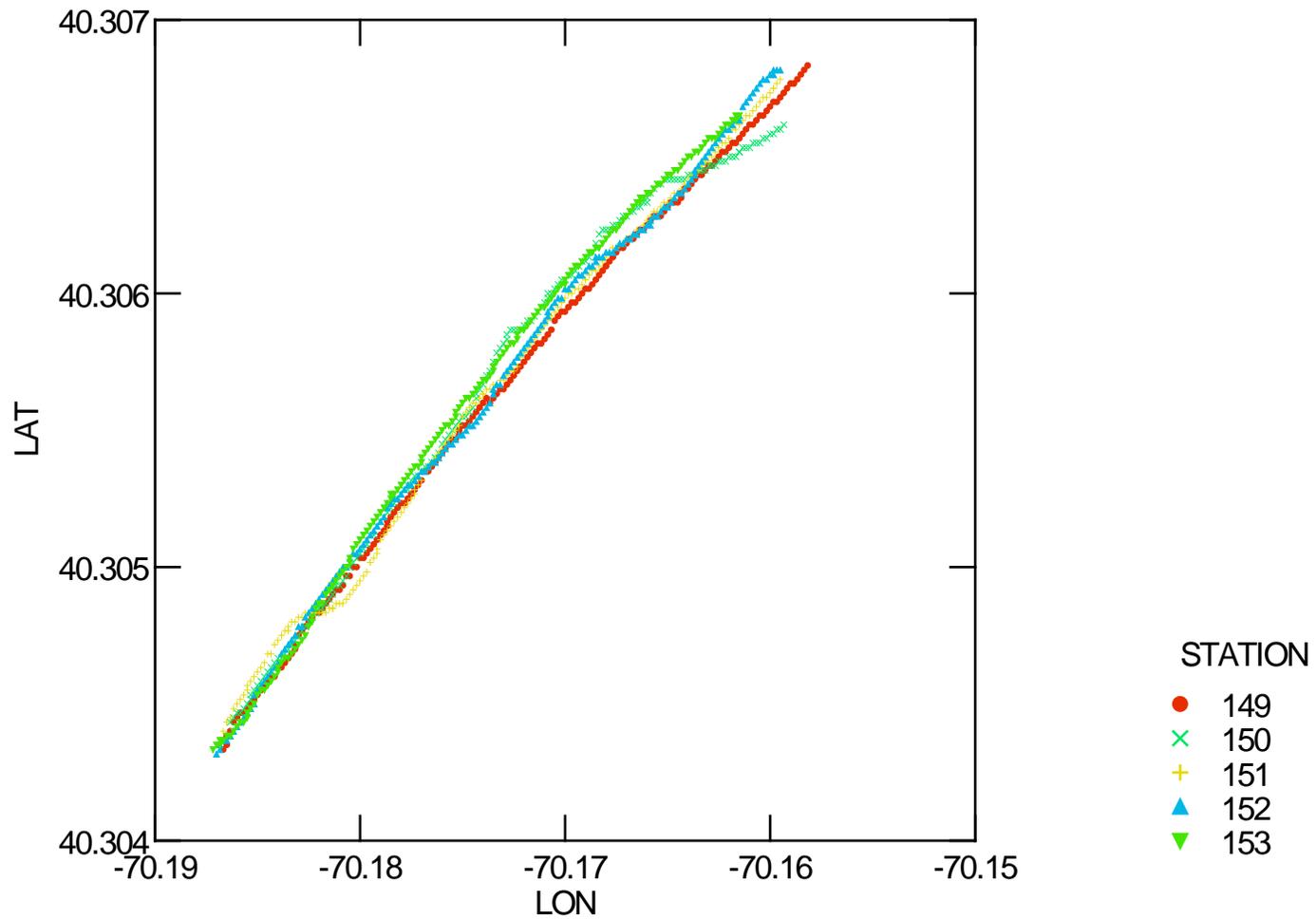


Experiment #3

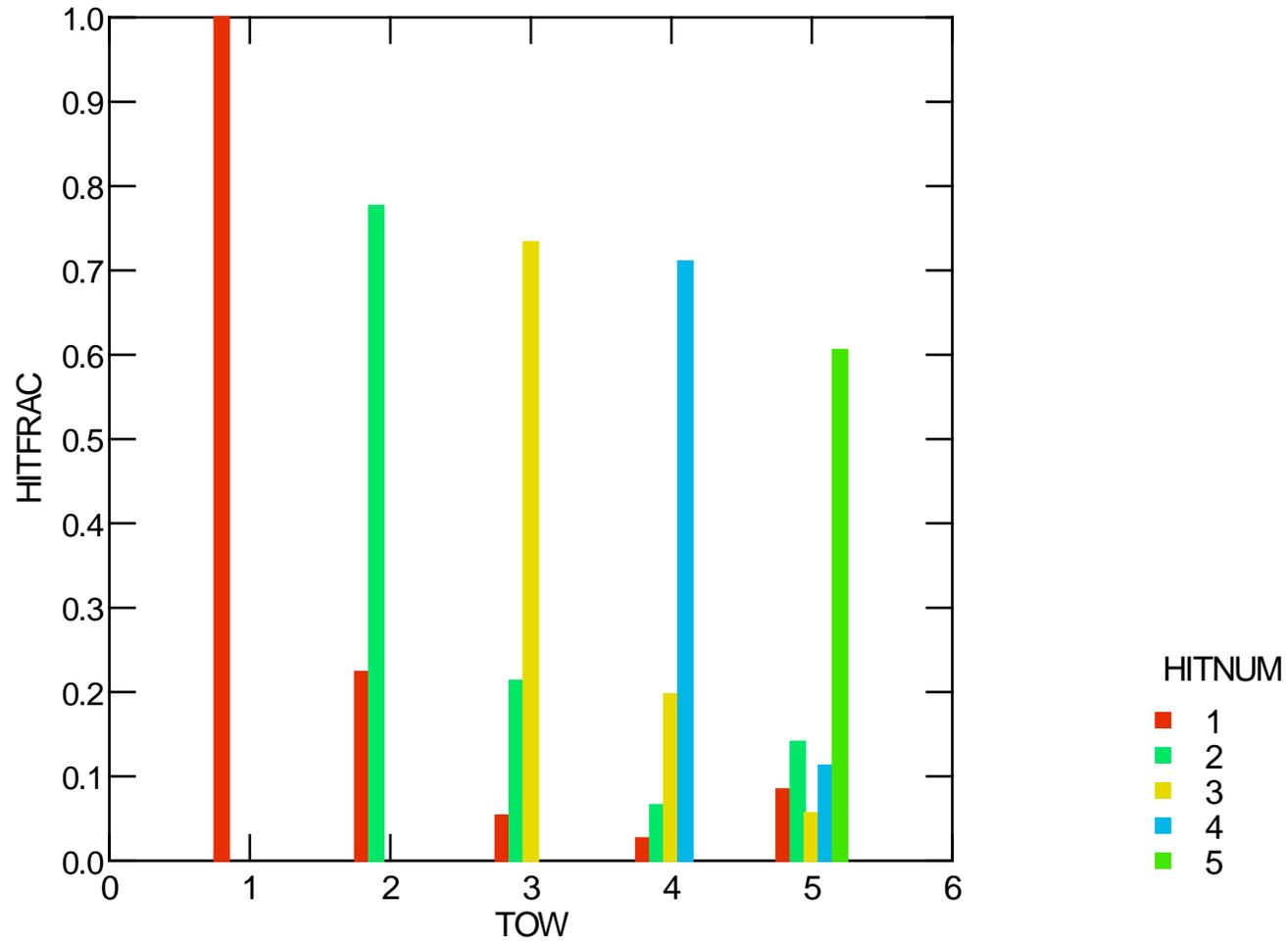


	Tow	Area Swept	Efftv Area	C_5%	C_50%	C_pred	OBS	C_95%
CI	1	634514.0	346094.2	21.	32.	32.	39.	46.
CI	2	590274.0	192848.7	11.	18.	18.	10.	28.
CI	3	597123.0	143012.4	8.	14.	13.	14.	22.
CI	4	612709.0	89918.2	5.	9.	8.	7.	15.
CI	5	562786.0	43035.3	2.	5.	4.	6.	9.

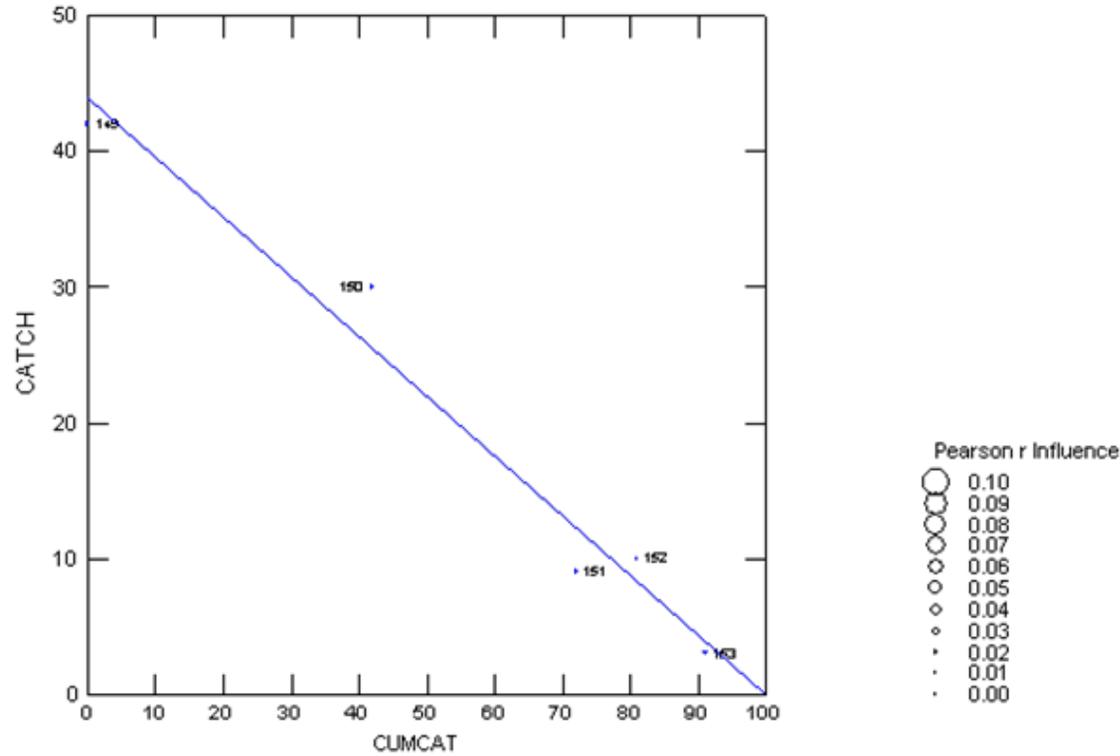
experiment #4



Experiment #4

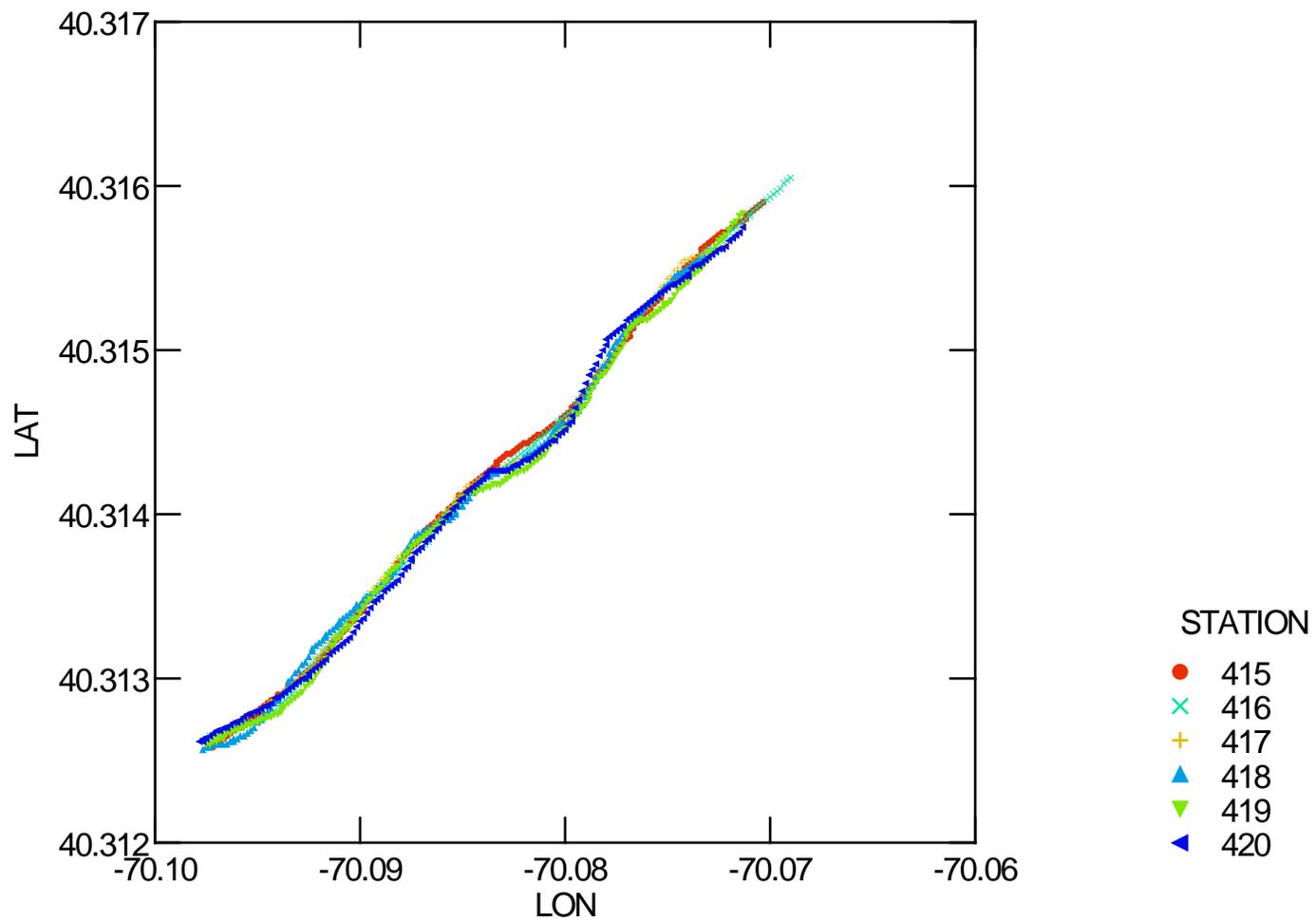


Experiment #4

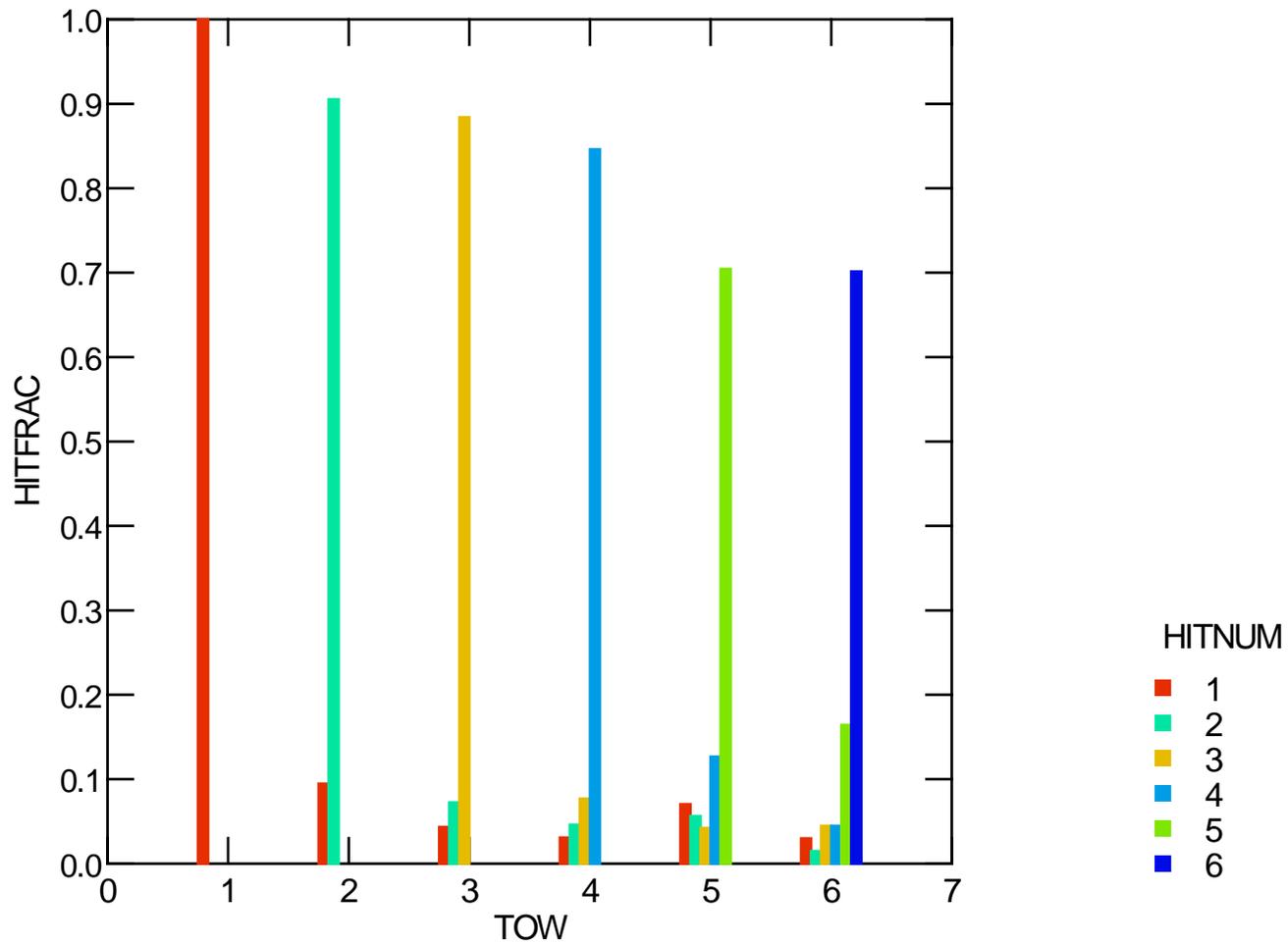


Tow	Area Swept	Efftv Area	C_5%	C_50%	C_pred	OBS	C_95%
CI 1	623017.0	425046.3	34.	44.	43.	42.	56.
CI 2	586683.0	230645.1	17.	24.	24.	30.	33.
CI 3	592784.0	121917.5	8.	13.	12.	9.	20.
CI 4	603661.0	67315.5	4.	8.	7.	10.	12.
CI 5	561273.0	75208.0	4.	9.	8.	3.	14.

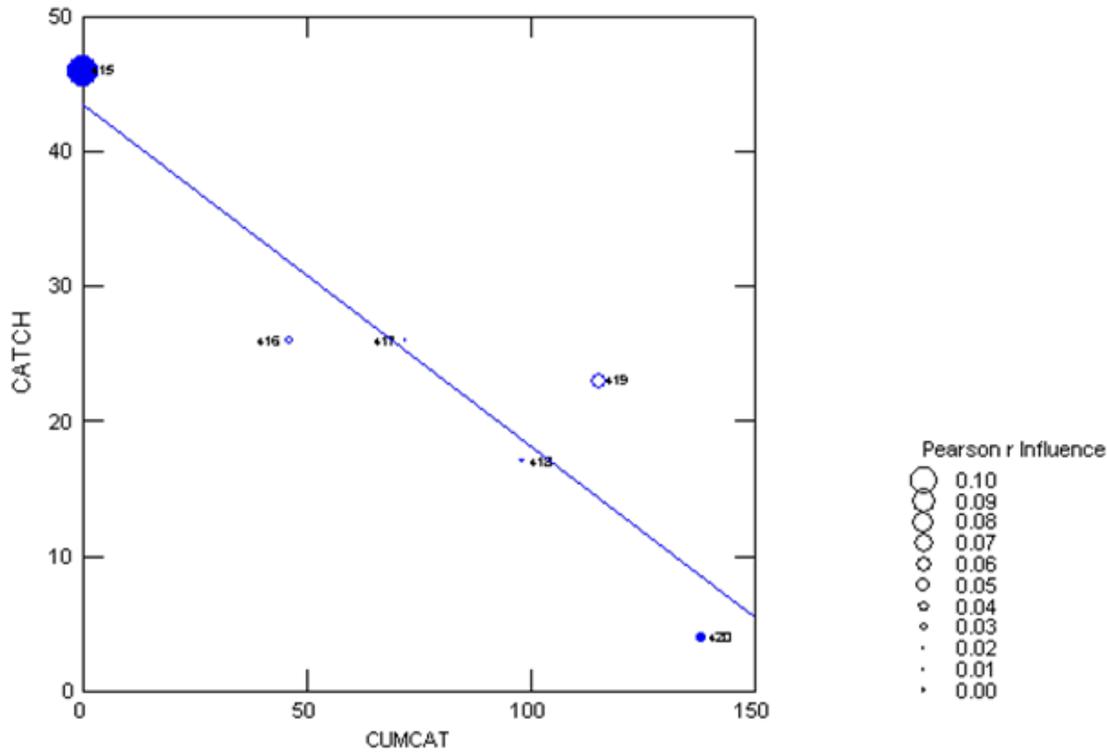
experiment #5



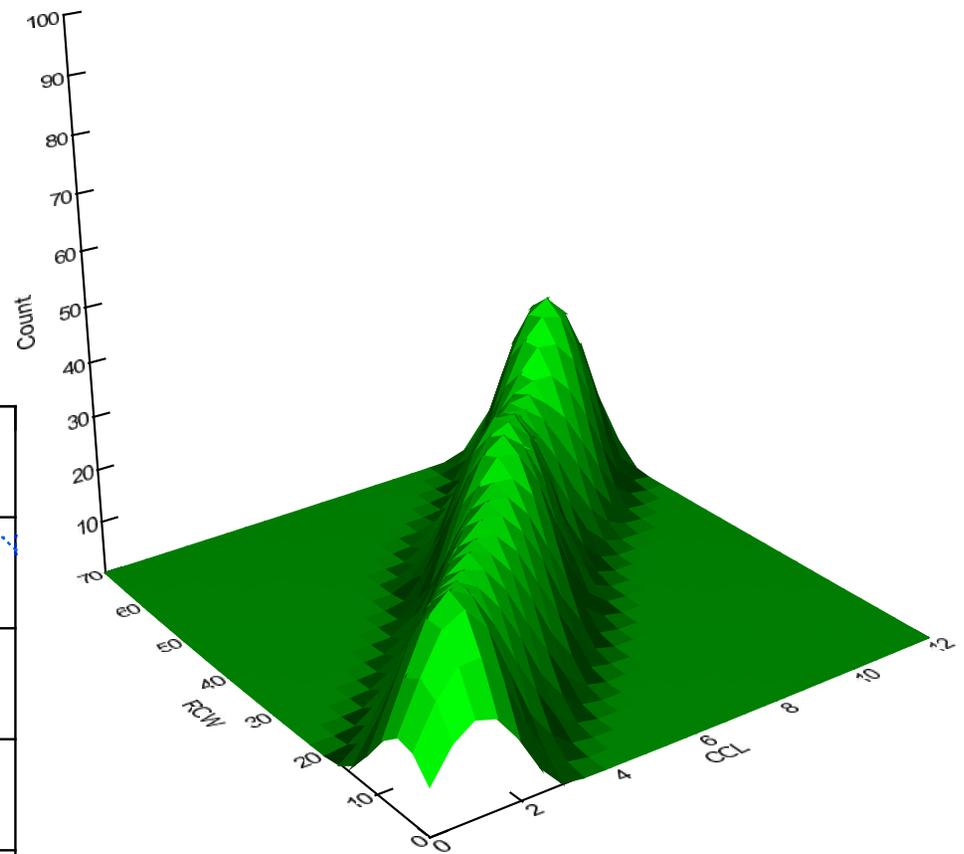
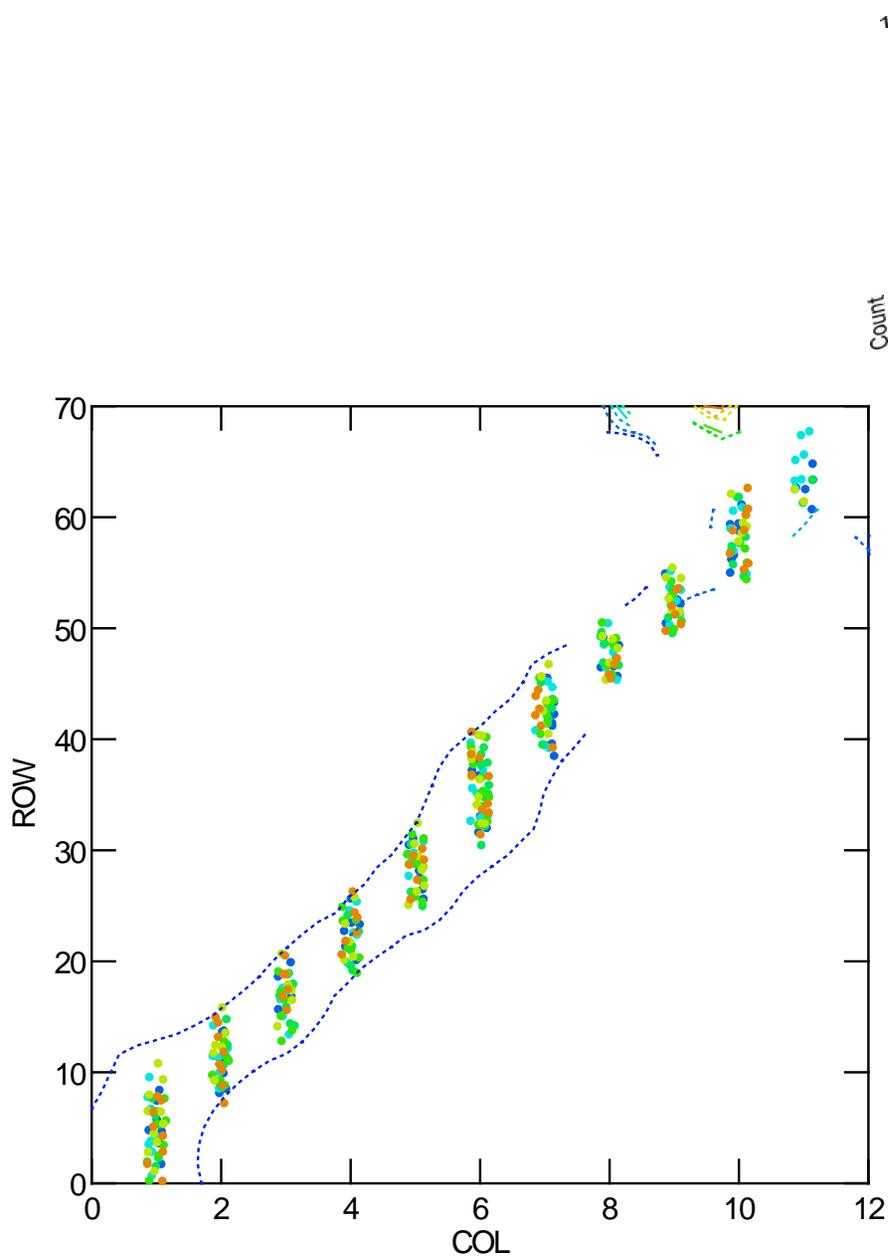
Experiment #5



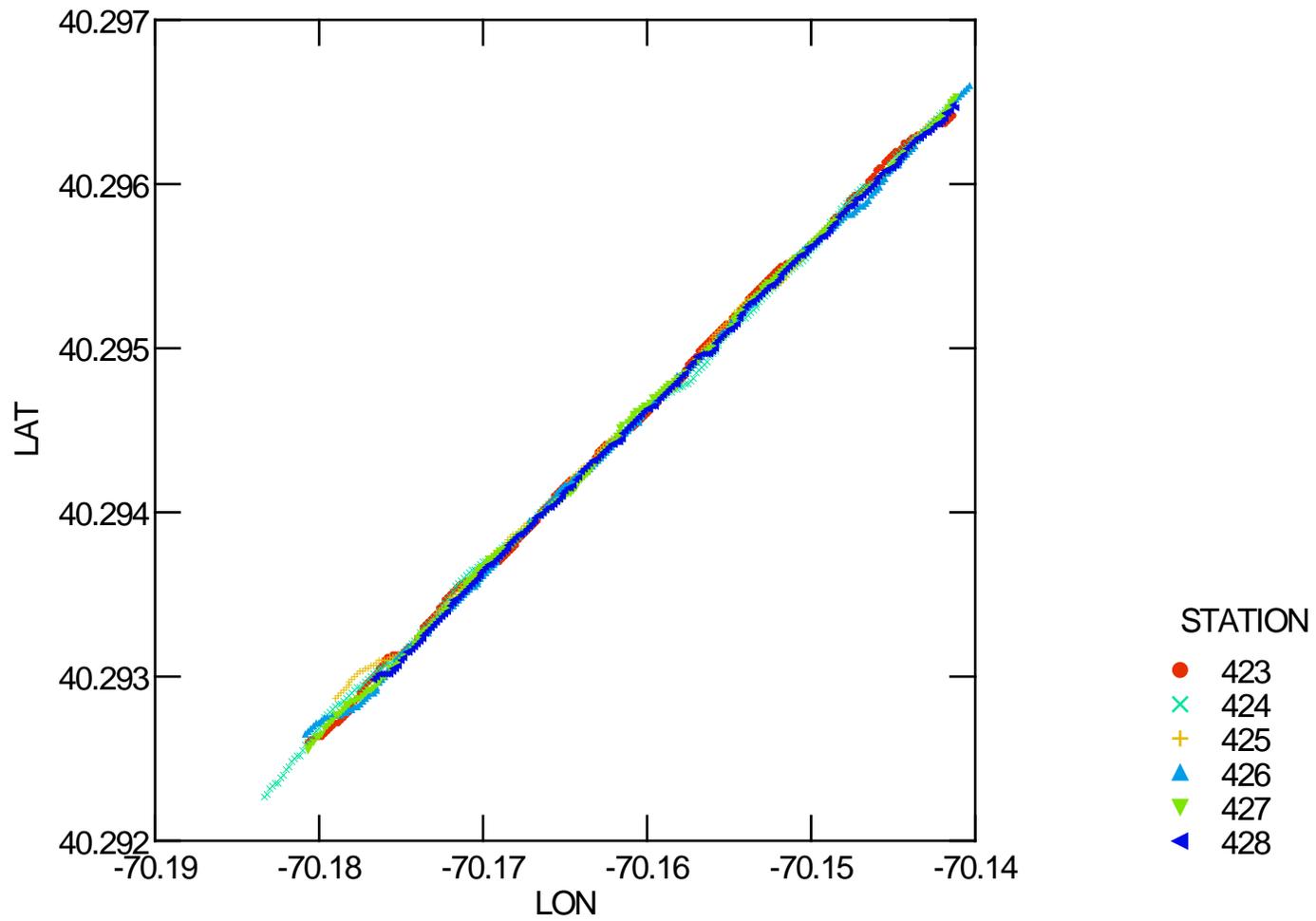
Experiment #5



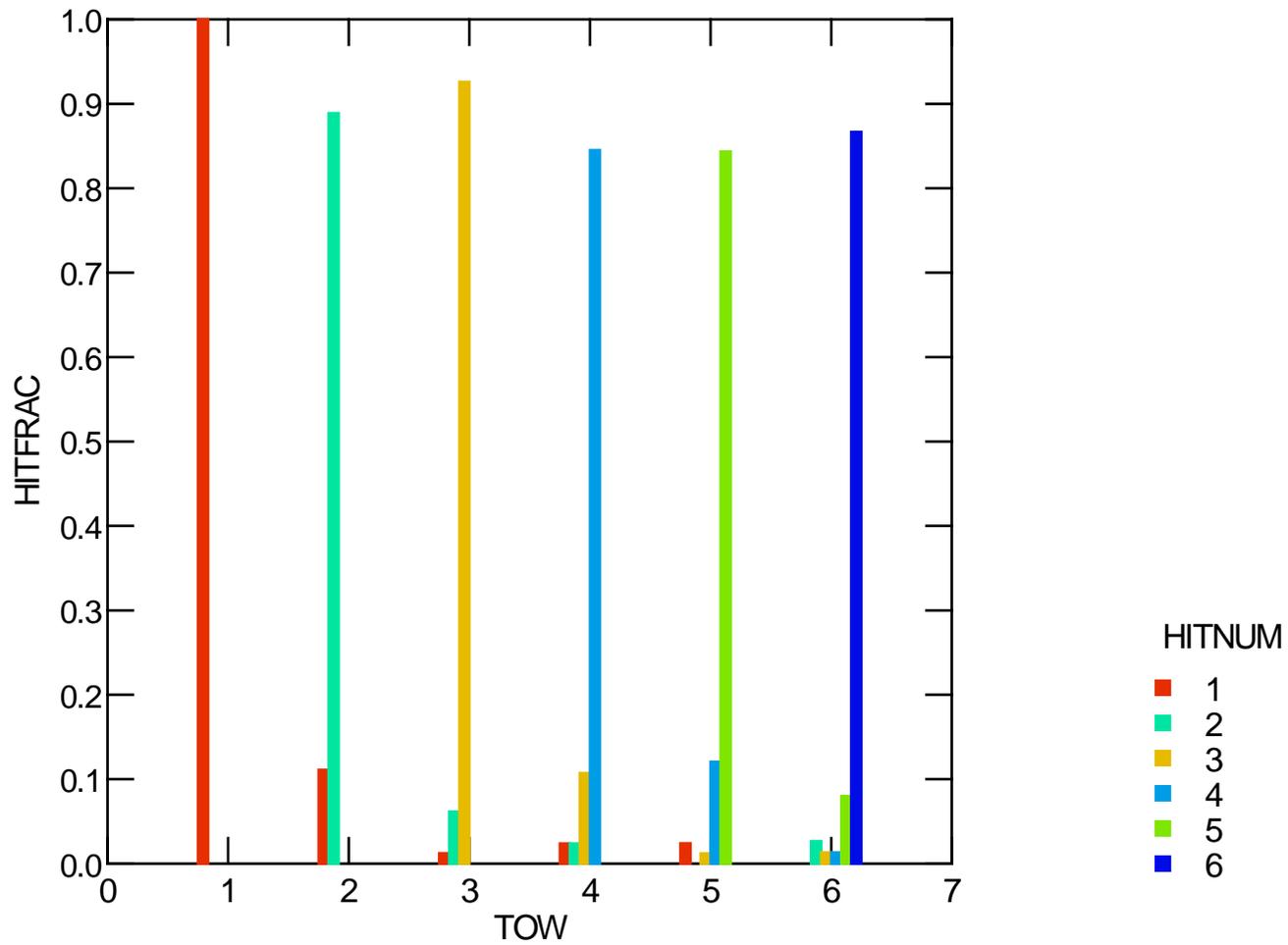
Tow	Area Swept	Efftv Area	C_5%	C_50%	C_pred	OBS	C_95%
CI 1	682690.0	261011.9	30.	46.	45.	46.	65.
CI 2	724422.0	200259.1	23.	35.	35.	26.	51.
CI 3	655756.0	130296.5	14.	23.	23.	26.	35.
CI 4	615450.0	90080.8	9.	16.	16.	17.	25.
CI 5	658380.0	84510.7	9.	15.	15.	23.	24.
CI 6	667457.0	58153.5	6.	11.	10.	4.	18.



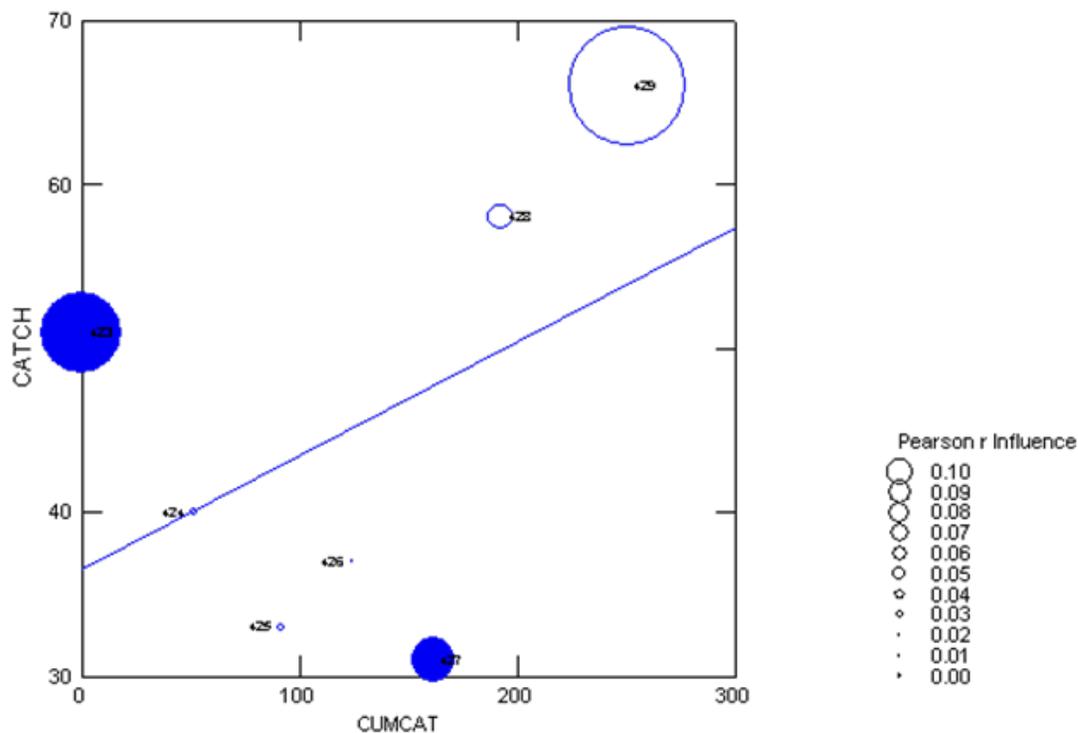
experiment #6



Experiment #6

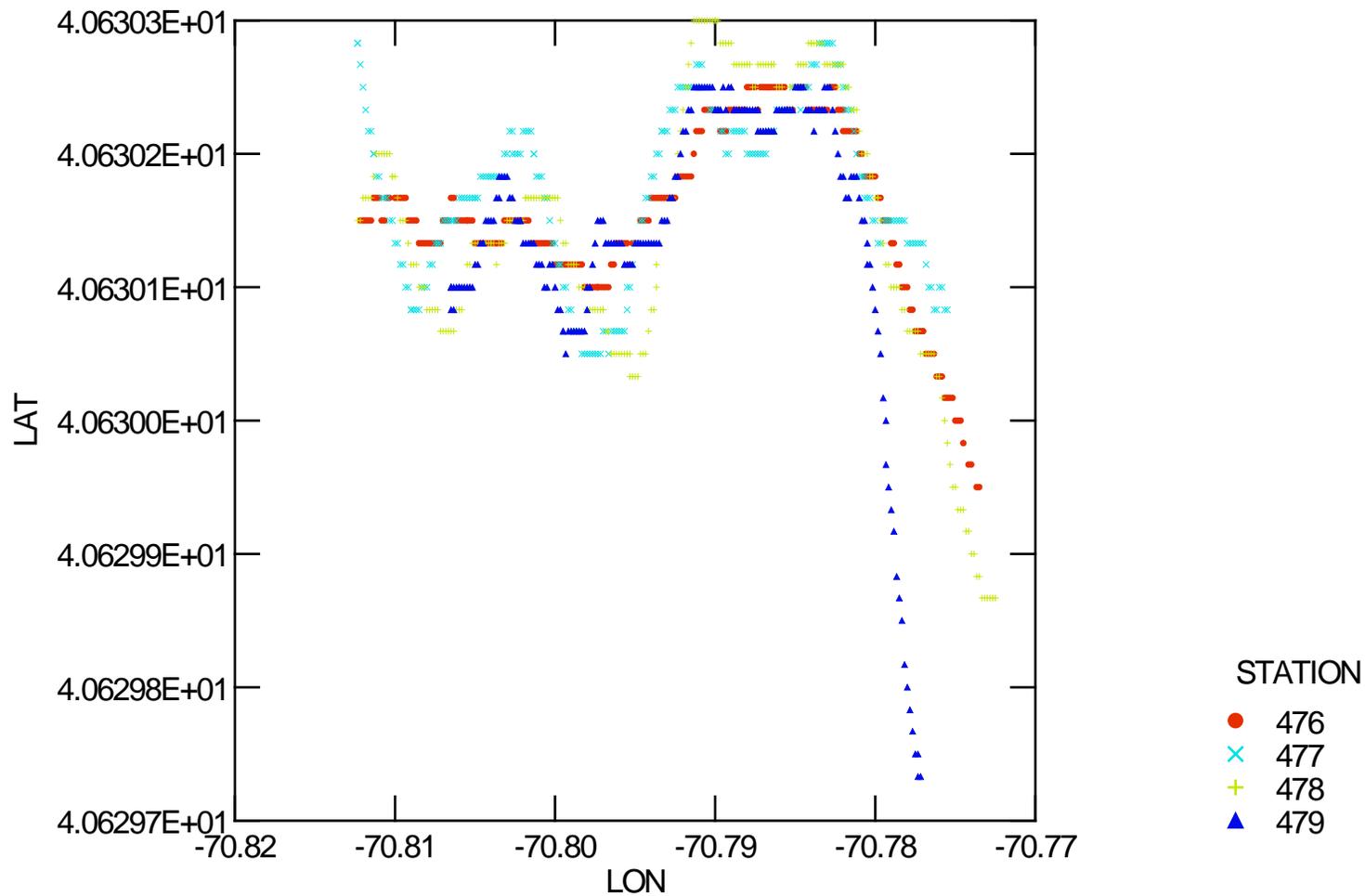


Experiment #6

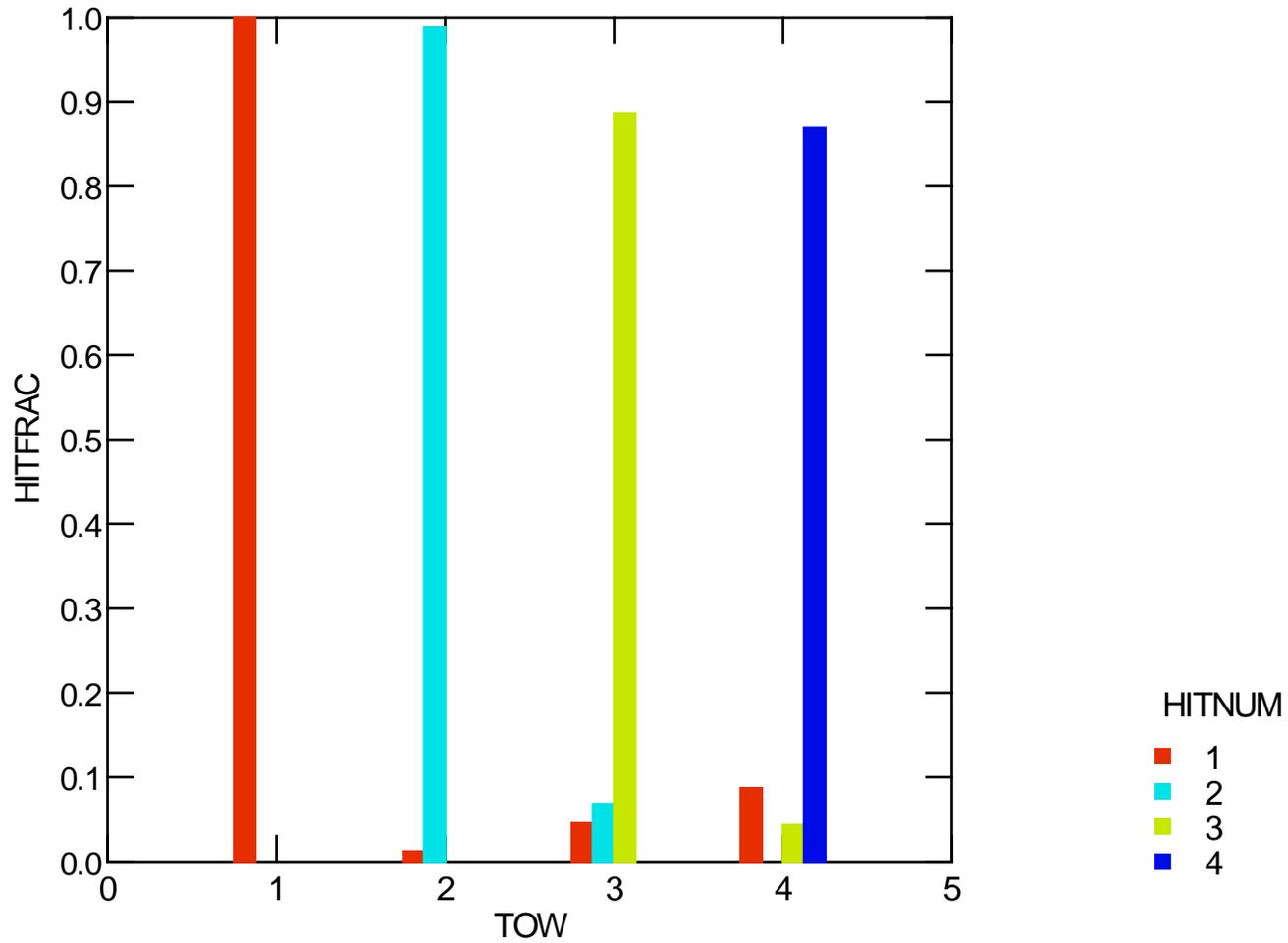


	Tow	Area Swept	Efftv Area	C_5%	C_50%	C_pred	OBS	C_95%
CI	1	1149328.0	57466.9	28.	47.	47.	51.	71.
CI	2	1228838.0	59257.8	29.	48.	48.	40.	73.
CI	3	1101188.0	50926.9	25.	41.	41.	33.	63.
CI	4	1180802.0	52736.3	26.	43.	43.	37.	65.
CI	5	1158107.0	49689.5	24.	40.	40.	31.	62.
CI	6	1031628.0	42518.2	20.	35.	34.	58.	53.

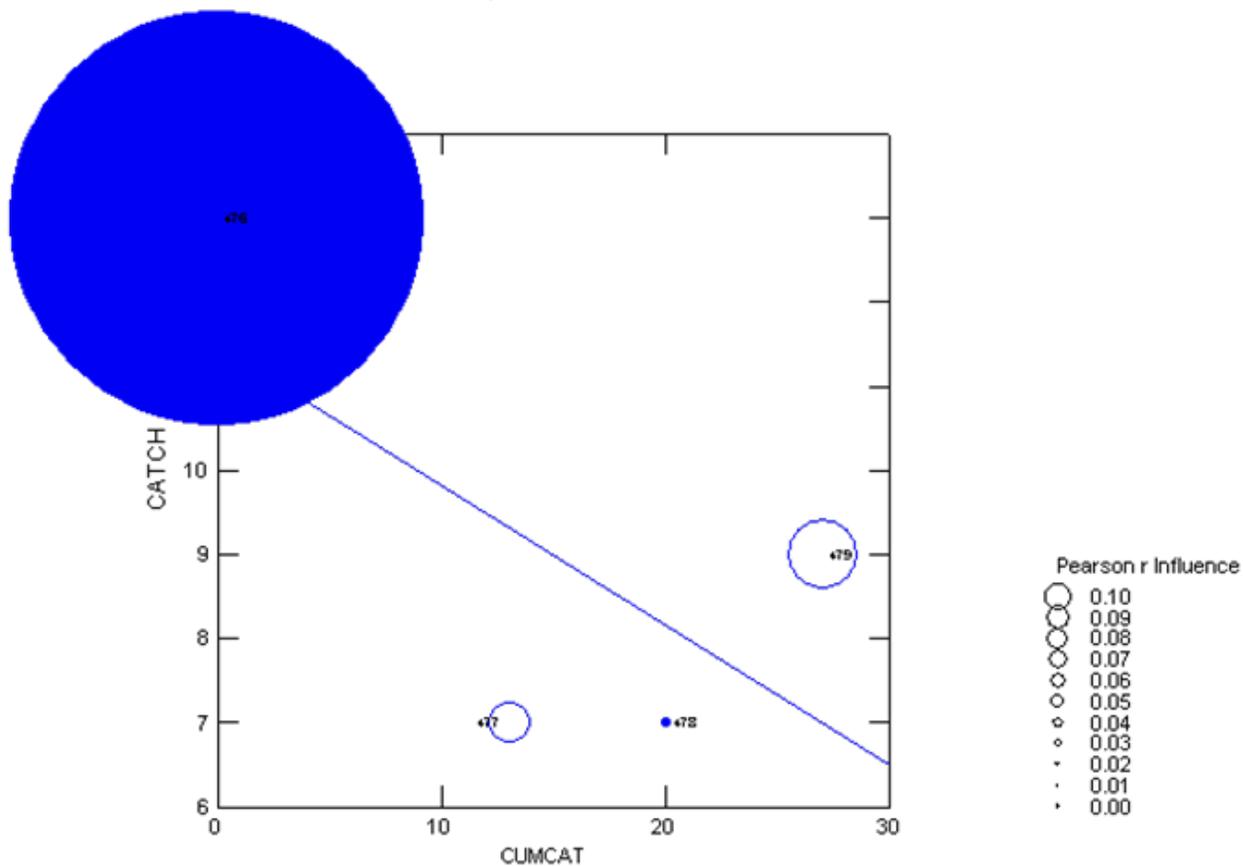
experiment #7



Experiment #7

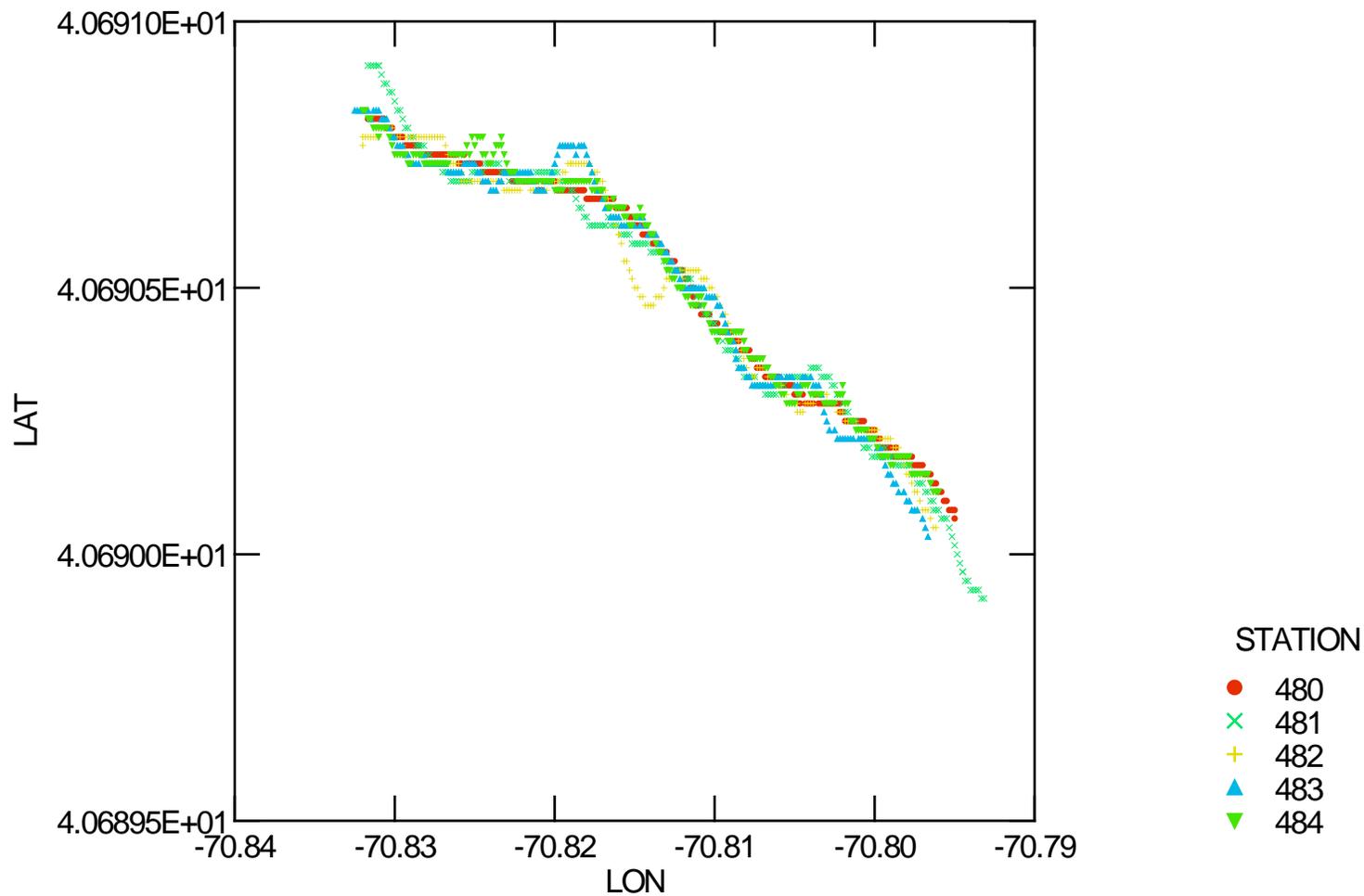


Experiment #7

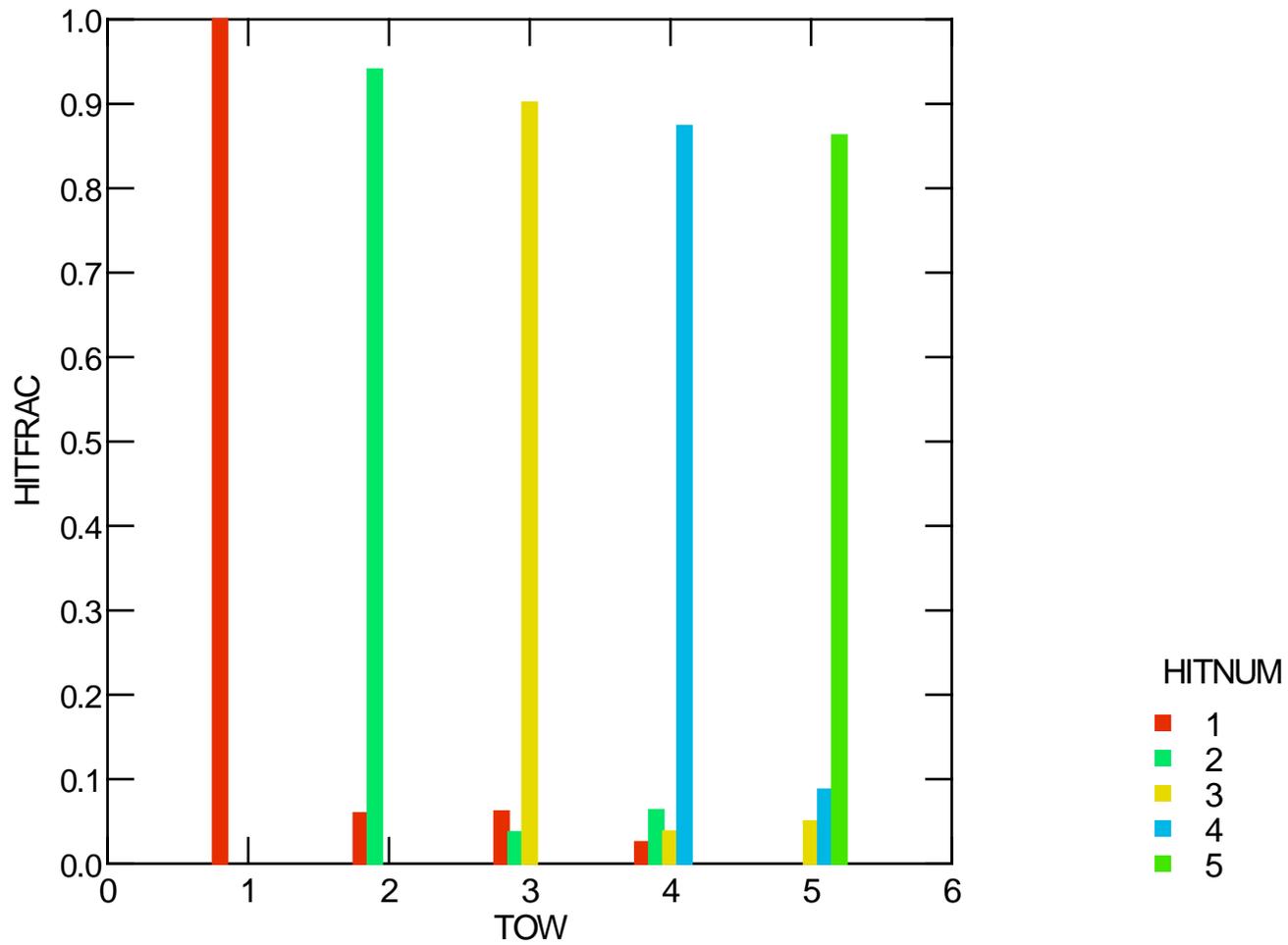


	Tow	Area Swept	Efftv Area	C_5%	C_50%	C_pred	OBS	C_95%
CI	1	928448.0	107975.1	7.	12.	11.	13.	17.
CI	2	894369.0	94451.2	6.	10.	9.	7.	16.
CI	3	966692.0	94029.9	6.	10.	9.	7.	16.
CI	4	719680.0	64567.9	4.	7.	6.	9.	12.

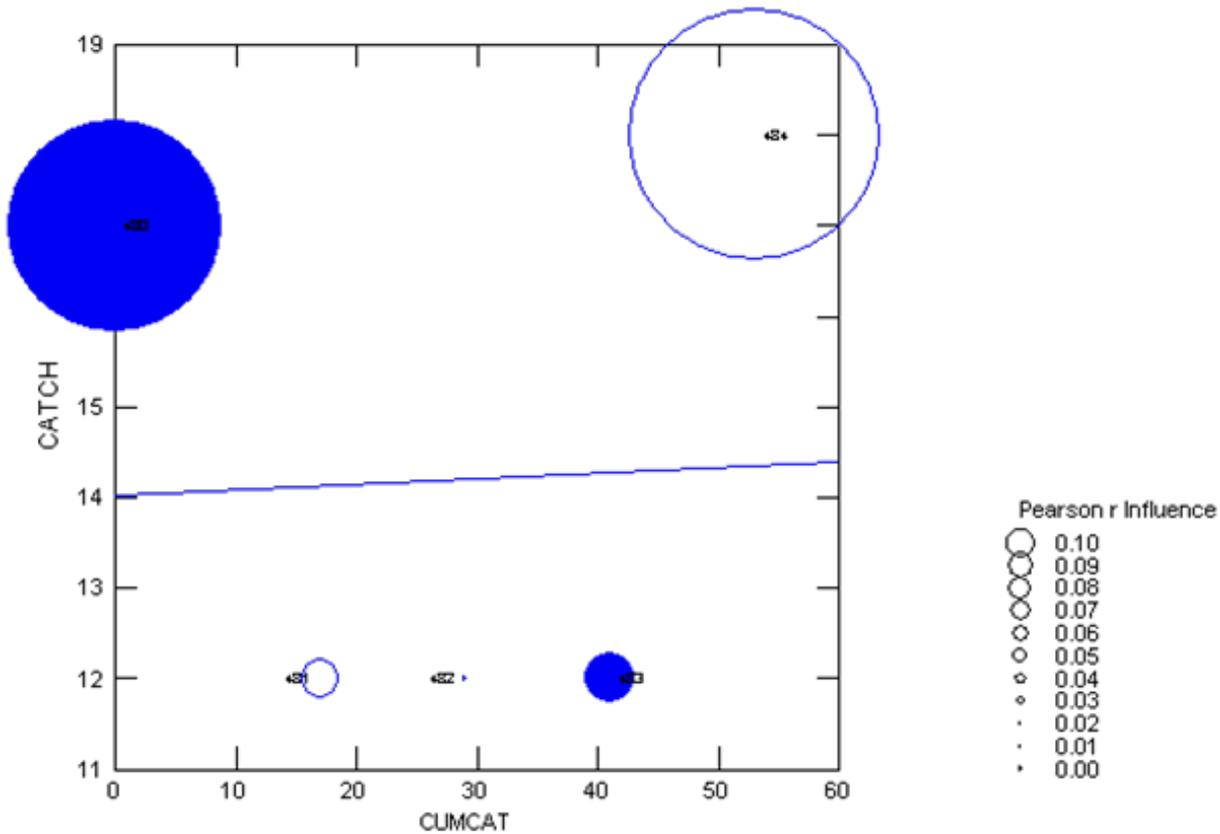
experiment #8



Experiment #8



Experiment #8



Tow	Area Swept	Efftv Area	C_5%	C_50%	C_pred	OBS	C_95%
CI 1	926410.0	46320.6	10.	16.	15.	17.	23.
CI 2	969823.0	46667.1	10.	16.	16.	12.	23.
CI 3	899735.0	41741.6	9.	15.	14.	12.	21.
CI 4	891727.0	39852.1	9.	14.	13.	12.	21.
CI 5	904538.0	38716.8	8.	14.	13.	18.	20.